DIQ/S 182 XT
System 182

MODULAR MEASURING SYSTEM FOR 2 DIGITAL SENSORS (DIQ/S 182 + DIQ/CR3)
For the most recent version of the manual, please visit [www.ysi.com](http://www.ysi.com).

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1 Components / scope of delivery System 182

Main components

Scope of delivery
The DIQ/S 182 Universal Transmitter is delivered with an attached DIQ/CR3 combination output module.

Note
Usage of the DIQ/CR3 is possible in conjunction with the System 182 only.

Operating manual
The operating manual consists of three parts:
Part 1: The part at hand with the description of the entire system
Part 2: Operating manual of the DIQ/S 182 (standard model)
Part 3: Operating manual of the DIQ/CR3 combination output model

2 Installation

Note
If any sensors with ultrasound cleaning function (e.g. VisoTurb 700 IQ or ViSolid 700 IQ) are permanently in use in an environment with temperatures over 50 °C (122 °F), an additional power supply module is required.
3 Outputs of the scope of delivery System 182

3.1 Available outputs of the components

Warning
If the outputs are connected incorrectly, there may be a danger to life from electric shock. Observe the operating manuals of the DIQ/S 182 and DIQ/CR3, especially the chapters SAFETY and INSTALLATION.

Outputs in the DIQ/S 182
- Relay output R1
- Relay output R2
- mA output C1

Outputs in the DIQ/CR3
- Relay output R1
- Relay output R2
- Relay output R3
- mA output C1
- mA output C2
- mA output C3

Fig. 3-1 Terminal strip of the DIQ/S 182 in the set System 182

Fig. 3-2 Terminal strip of the DIQ/S 182/24V in the set System 182

Fig. 3-3 Terminal strip of the DIQ/CR3
3.2 Setting outputs

Setting the outputs of the System 182

The outputs are listed in the SETTINGS menu:

<table>
<thead>
<tr>
<th>SETTINGS</th>
<th>Language</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>S01 TriOxmatic700IQ</td>
</tr>
<tr>
<td></td>
<td>S02 TetraCon700IQ</td>
</tr>
<tr>
<td>D00 DIQ/S182</td>
<td>R1 ↓</td>
</tr>
<tr>
<td>D00 DIQ/S182</td>
<td>R2</td>
</tr>
<tr>
<td>D00 DIQ/S182</td>
<td>C1</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>R1</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>R2</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>R3</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>C1</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>C2</td>
</tr>
<tr>
<td>D01 DIQ/CR3</td>
<td>C3</td>
</tr>
</tbody>
</table>

Fig. 3-4 Submenus in the SETTINGS menu of the System 182

The relay outputs and current outputs of the DIQ/S 182 and DIQ/CR3 have the same functions and setting options.

3.3 Checking the status of the outputs

The current states of all outputs can be called up via the measured value and status display. Pressing several times switches cyclically between the individual display options of the measured value and status display until the outputs are displayed. Scroll to further pages with states of outputs with .

Example:

<table>
<thead>
<tr>
<th>03-Nov-05 14:54</th>
<th>D01 DIQ/CR3</th>
</tr>
</thead>
<tbody>
<tr>
<td>R1: — C1: 1.44 ↑</td>
<td>R1: — C1: 1.44 ↑</td>
</tr>
<tr>
<td>R2: —</td>
<td>R2: — C2: 0.16</td>
</tr>
<tr>
<td></td>
<td>R3: — C3: 0.00 ↓</td>
</tr>
</tbody>
</table>

Fig. 3-5 Outputs in the measured value and status display
DIQ/S 182
System 182
MODULAR MEASURING SYSTEM FOR 2 DIGITAL SENSORS
For the most recent version of the manual, please visit www.ysi.com.

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1 Overview

1.1 Structure and function

The System 182 is a modular, multiparameter measuring system. The control and operation unit of the system is the DIQ/S 182 Universal Transmitter with integrated power pack. It has three relay outputs and two current outputs to be connected to existing process control systems.

**Sensors**

One or two digital YSI single sensors (one sensor for one main measured parameter) or a double sensor (one sensor for two main measured parameters) can be connected to the DIQ/S 182 Universal Transmitter. I. e. up to two main measured parameters (e.g. pH, D. O. content, turbidity value...) and additionally up to two secondary measured parameters (e.g. temperature) can be displayed and administrated. Each sensor is automatically recognized after being connected and immediately starts measuring.

One sensor can be directly connected to the DIQ/S 182 Universal Transmitter. Connecting two sensor requires the DIQ/J B branching module (accessory). The DIQ/J B branching module is a simple passive module for the branching of IQ SENSOR NET lines.

![Diagram of System 182 components](image)

Fig. 1-1 Simple systems with one and two sensors
The relay and current outputs can be linked with sensors. Linked outputs can be used to monitor sensors and for the output of measured values.

A relay output is programmable as:
- Monitoring relay
- Limit monitor
- Proportional output of measured values (pulse width or frequency output)
- Control unit of a compressed air-driven sensor cleaning system.

A current output is programmable as:
- Analog output
- PID controller

For quick orientation, the states of all relay and current outputs are clearly indicated on the display.

The DIQ/S 182 Universal Transmitter is prepared for the compressed air-driven, time-controlled sensor cleaning function. For this, a DIQ/CHV valve module and if necessary a CH cleaning head is required per sensor (both available as accessories). The cleaning procedure is controlled by the Universal Transmitter. The Universal Transmitter provides the supply voltage and control relay for the compressed air valve in the DIQ/CHV valve module. This enables a simple setup and uncomplicated wiring.

Alternatively, the MIQ/CHV PLUS valve module can be installed in the system. It combines the relay, valve and valve power supply in one MIQ enclosure. Thus, no additional wiring is required, which makes installation easier especially if the distance between the Universal Transmitter and sensor is great.

If necessary, an additional power pack can be added to supply sensors with high power consumption (e.g. UV/VIS sensor).
1.2 Behavior of the system in the case of power failure

- The system configuration remains stored permanently. It consists of the following settings:
  - Sensor settings
  - Settings and links of relay outputs
  - Settings and links of current outputs
  - System settings (display language, air pressure/location altitude, passwords, etc.)
- Linked relay outputs switch to the non-active condition (open).
- Linked current outputs switch to the non-active condition (0 mA).
- When the power is restored the system is automatically restarted. The system continues to work with the settings at the time of the power failure (except for the time).
2  Safety

2.1  Safety information

2.1.1  Safety information in the operating manual

This operating manual provides important information on the safe operation of the product. Read this operating manual thoroughly and make yourself familiar with the product before putting it into operation or working with it. The operating manual must be kept in the vicinity of the meter so you can always find the information you need.

Important safety instructions are highlighted in this operating manual. They are indicated by the warning symbol (triangle) in the left column. The signal word (e.g. "CAUTION") indicates the danger level:

**WARNING**
indicates a possibly dangerous situation that can lead to serious (irreversible) injury or death if the safety instruction is not followed.

**CAUTION**
indicates a possibly dangerous situation that can lead to slight (reversible) injury if the safety instruction is not followed.

**NOTE**
indicates a possibly dangerous situation where goods might be damaged if the actions mentioned are not taken.

2.1.2  Safety signs on the product

Note all labels, information signs and safety symbols on the product. A warning symbol (triangle) without text refers to safety information in this operating manual.

2.1.3  Further documents providing safety information

The following documents provide additional information, which you should observe for your safety when working with the measuring system:

- Operating manuals of other components of the DIQ/S 182 system (power packs, controller, accessories)
- Safety datasheets of calibration and maintenance equipment (e.g. cleaning solutions).
2.2  Safe operation

2.2.1  Authorized use

The authorized use of the System 182 consists of its use in online analysis. Only the operation and running of the product according to the instructions and technical specifications given in this operating manual is authorized (see chapter 9 TECHNICAL DATA). Any other use is considered unauthorized.

2.2.2  Requirements for safe operation

Note the following points for safe operation:

- The product may only be operated according to the authorized use specified above.
- The product may only be supplied with power by the energy sources mentioned in this operating manual.
- The product may only be operated under the environmental conditions mentioned in this operating manual.
- The product may not be opened.

2.2.3  Unauthorized use

The product must not be put into operation if:

- it is visibly damaged (e.g. after being transported)
- it was stored under adverse conditions for a lengthy period of time (storing conditions, see chapter 9 TECHNICAL DATA).

2.3  User qualification

Target group

The DIQ/S 182 system was developed for online analysis. Some maintenance activities, e.g. changing the membrane caps in D.O. sensors, require the safe handling of chemicals. Thus, we assume that the maintenance personnel is familiar with the necessary precautions to take when dealing with chemicals as a result of their professional training and experience.
Special user qualifications

The following installation activities may only be performed by a qualified electrician:

- Connection of the MIQ/PS power supply module to the power line (see MIQ/PS module manual).
- Connection of external, line voltage-carrying circuits to relay contacts (see module manual of the relay output module).

WARNING

A circuit (except for the power supply connections), that is connected to an DIQ/S 182 component, must not feed any voltages or currents that are not allowed. It has to be made sure that the circuit at any time meets all requirements of a Limited circuit or Limited Power as well as of SELV (Safety Extra Low Voltage). These include the following limiting value specifications:

- AC voltage: max. 30 V effective / 42.4 V peak
- DC voltage: max. 60 V
- Current limit: max. 8 A
- Power output limitation: max. 150 VA
3 Installation

3.1 Scope of delivery

The following parts are included in the scope of delivery of the DIQ/S 182:

- DIQ/S 182 Universal Transmitter
- Accessory kit with:
  - Contact carrier with screws
  - ISO cap nuts with screws and ring washers
  - Cable glands with sealing gaskets
- Operating manual.

3.2 Basic requirements for installation

3.2.1 Requirements of the measurement location

The measurement location must meet the environmental conditions specified in section 9.1 DIQ/S 182.

3.2.2 Additional MIQ power supply modules

The power pack of the Universal Transmitter supplies enough power for most combinations of sensors. Some sensors with high power consumption may require the installation of an MIQ power supply module in addition to the Universal Transmitter. For installation, refer to the operating manual of the power supply module. The table on the following page shows which sensor/sensor combinations require an additional power supply module.

The terminator switch on the terminal strip of all additional MIQ modules in the system 182 must be set to “Off”.
### Installation

**System 182**

<table>
<thead>
<tr>
<th>1st sensor</th>
<th>TriOxmatic® 700 IQ (SW)</th>
<th>TriOxmatic® 701 IQ</th>
<th>TriOxmatic® 702 IQ</th>
<th>FDO® 700 IQ (SW)</th>
<th>TetraCon® 700 IQ (SW)</th>
<th>AmmoLy® Plus 700 IQ</th>
<th>NitraLy® Plus 700 IQ</th>
<th>Sensol® 700 IQ (SW)</th>
<th>ViS® Solid® 700 IQ</th>
<th>ViS® TUR® 700 IQ</th>
<th>NitraVis® 705 IQ *</th>
<th>CarboVis® 705 IQ *</th>
<th>VARiON® Plus 700 IQ (NH₄-N or NO₃-N)</th>
<th>MIQ/IC2 (1 channel operation)</th>
</tr>
</thead>
<tbody>
<tr>
<td>TriOxmatic® 700 IQ (SW)</td>
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<td>TriOxmatic® 701 IQ</td>
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<td>TriOxmatic® 702 IQ</td>
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<td>TetraCon® 700 IQ (SW)</td>
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<tr>
<td>AmmoLy® Plus 700 IQ</td>
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<td>NitraLy® Plus 700 IQ</td>
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<tr>
<td>VARiON® Plus 700 IQ (NH₄-N or NO₃-N)</td>
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<td>- (double sensor: no combination with any other sensor possible!)</td>
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<tr>
<td>SensoLy® 700 IQ (SW)</td>
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<tr>
<td>ViS® Solid® 700 IQ</td>
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<tr>
<td>ViS® TUR® 700 IQ</td>
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<td>1 (double sensor: no combination with any other sensor possible!)</td>
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<tr>
<td>MIQ/IC2 (1 channel operation)</td>
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<td>-</td>
<td>- (double sensor: no combination with any other sensor possible!)</td>
</tr>
</tbody>
</table>

1 = One additional power supply module required.

* Install a further MIQ power supply module in the vicinity of the sensor.
3.3 Safety requirements on the electrical installation

Electrical equipment (e.g. motors, contactors, cables, lines, relays) must meet the following requirements:

- Conformity with national regulations (e.g. NEC, VDE and IEC)
- Suitability for the electrical conditions at the installation site
  - Maximum operating voltage
  - Maximum operating current
- Suitability for the environmental conditions at the installation site
  - Temperature resistance (minimum and maximum temperature)
  - Stability against UV light when used outdoors
  - Protection against water and dust (Nema or IP protection class).
- Suitable fusing of the electrical circuit
  - Overcurrent fuses (in accordance with the technical data of the device input or output)
  - Overvoltage class II surge limiters
- Suitable disconnecting device (e.g. switch or circuit breaker) for the mains supply of permanently mounted equipment with separate mains connection
  - in compliance with the following regulations
    - IEC 60947-1
    - IEC 60947-3
  - in the vicinity of the equipment (recommendation)
- Flame-resistant (cables and lines), in compliance with the following regulations
  - UL 2556 VW-1 (for USA, Canada)
  - IEC 60332-1-2 (outside of USA, Canada)

3.4 Installation guidelines for lightning protection

When using the IQ SENSOR NET instrumentation, particularly in outdoor areas, adequate protection against (electrical) surges must be provided. A surge is a summation phenomenon of surge voltage and surge current. It is generated through the indirect effect of a lightning event or switching operation in the mains, in the grounding system and in information technology lines.

To be adequately protected against the damaging effects of surges, an integrated concept of the following protective measures is required:
• internal device-related protective measures and
• external protective measures of the installation environment.

The internal device-related protective measures are already integrated in the YSI online measuring technology as so-called 'lightning protection' (see chapter 9 TECHNICAL DATA).

The external protective measures of the installation environment can be carried out with respect to the following guidelines:

1 All lines of the IQ SENSOR NET system must be
   a) installed inside (or else close to) the grounded metallic mounting constructions, e.g. handrails, pipes and posts if possible
   b) or, particularly in the case of longer lines, laid in the ground.

   Background: The formation of highly lightning hazardous inductive loops between the cables and ground is avoided through the low clearance of the grounded metal construction or by installation in the ground.

2 Only the SNCIQ or SNCIQ-UG cable material must be used. This cable material, particularly the high line cross section of the cable shielding (1.5 mm²), is an important prerequisite for the hazard-free discharging of the surge without inadmissibly high overvoltages developing along the line at the same time that could have a damaging effect on the individual IQ SENSOR NET components. It is not recommended to use cables from other manufacturers with usually appreciably lower shielding conductor cross sections.

3 All metallic mounting constructions, handrails, pipes, posts etc. on which MIQ modules are installed must be connected to the local potential equalization system and the grounding system or must be individually sufficiently grounded locally according to the codes of practice.

   For the individual grounding of the measuring point the mounting construction must be solidly connected by means of a large-area auxiliary electrode with the measuring medium.
   Metallic control shafts/pipes and other large-area metallic bodies that reach into the measuring medium are, for example, ideal for use in the grounding of the mounting construction.
   This creates a set path for the main surge. As a result it is possible to avoid the surge being discharged via the IQ SENSOR NET cable and via the valuable sensors in the measuring medium.

4 The contacts of the MIQ modules must always be protected by the associated contact covers if they are not in use. The contact cover provides improved insulation against the electric fields of a thunderstorm event through the extension of the air and creepage paths.

5 It is recommended to attach a metallic or nonmetallic sun shield to each outside location of the MIQ modules. Sun shields protect the
electric field lines in the area of the MIQ module through an advantageous development of the electrical field lines in the area of the MIQ module and promote the dissipation of the surge via the mounting construction.

6 The mains voltage for supplying the measuring system must comply with overvoltage category II. Generally this is ensured through the public operator of the power supply networks. In company-owned networks, e.g. in all power supply systems owned by wastewater treatment plants, this must be kept separate by a potential equalization and a surge protection system for the plant.

7 One part of the IQ SENSOR NET safety and lightning protection concept is based on high-grade protective insulation of the network components and of the entire system. It does not have or require any protective ground (PG) conductor or earth terminal. Avoid any direct connection of the IQ SENSOR NET connections or the metallic sensor enclosures with the local grounding or potential equalization system and with metallic construction elements (see point 9).

8 Additional external lightning protection measures directly on the IQ SENSOR NET system or its components, e.g. the use of overvoltage surge arresters, are not necessary for protection against the indirect effects of lightning and could possibly result in malfunctions.

9 For the realization of the internal lightning protection of the system (e.g. wastewater treatment plant control stands) and for the protection of IQ SENSOR NET external resources, cable entry points into buildings or distributions coming from the IQ SENSOR NET must be carried out as follows:

- The shield of SNCIQ or SNCIQ-UG cables can be connected to the local potential equalization with a gas overvoltage surge arrester. Use shield clamps for the contacting of the shield. The shield of the cable must not be opened under any circumstances.

- 0/4-20 mA interfaces must be realized with shielded cables. The cable shield must be connected directly to the potential equalization(s) provided. If plant potential equalization systems are provided on both sides, the shield must also be connected on both sides. The inner conductors must have no contact with the potential equalization.

- Relay lines should be connected to the local potential equalization in order to provide general and consistent protection via gas overvoltage surge arresters.
3.5 Connecting system components

3.5.1 Connecting MIQ modules: General information

You can connect the Universal Transmitter to MIQ modules without connection cable (stack mounting).

**Mounting direction**

**Variant 1** - stack expansion forwards.

The back of the Universal Transmitter or an MIQ module is attached to the lid of an MIQ module (page 3-8).

Select this variant if an MIQ module is already permanently installed, e.g. to a wall.

**Variant 2**: - stack expansion backwards.

The lid of an MIQ module is attached to the back of the Universal Transmitter or another MIQ module (page 3-11).

Select this variant if the Universal Transmitter or other MIQ module is already permanently installed, e.g. in a panel.

**NOTE**

For optimum stability, a maximum of two MIQ modules may be connected to the Universal Transmitter. One MIQ power supply module
**Materials required**

- 2 x ISO blind nuts (M4)
- 2 x cheese-head screws (M4x16) with plastic washer
- 1 x contact base with two plastic tapping screws (scope of delivery of the MIQ module).

**Tools**

- Phillips screwdriver.

Below, both installation variants of attaching an MIQ module to the Universal Transmitter are described. The assembly of further MIQ modules is carried out analogously. To dismantle a stack, proceed in the reverse order to mounting.

In the case of panel mounting, the front module must be installed individually in the switch cabinet aperture first. Only then can any MIQ modules be added (variant 2).

The terminator switch on the terminal strip of all MIQ modules in the System 182 must be set to "Off".

*only may be mounted per stack in addition to the Universal Transmitter.*
3.5.2 Variant 1: Stack expansion forwards

Preparing the stack mounting

1. Remove the covers from the drilled mounting holes (pos. 1 and 3 in Fig. 3-1).
2. Remove the contact cover (pos. 2).
3. Pull off the adhesive label (pos. 4).

Mounting the contact base

Only use the plastic tapping screws supplied for attaching the contact base. They ensure the correct fit.
4. Attach the contact base (pos. 5 in Fig. 3-2) on the Universal Transmitter with the two plastic tapping screws (pos. 6).

5. On the Universal Transmitter, remove the two countersunk screws (pos. 7 in Fig. 3-2) and swing open the lid.

6. Insert the cheese-head screws (pos. 8 in Fig. 3-3) with the plastic washers in the drilled mounting holes in the enclosure and loosely screw in the ISO blind nuts (pos. 9).
Attach the prepared Universal Transmitter to the lid of the MIQ module. At the same time, ensure that the two clips on the Universal Transmitter click into place in the lid of the MIQ module. Subsequently, tighten the two screws (pos. 8 in Fig. 3-3).

Close the lid of the Universal Transmitter and fix it with the two countersunk screws (pos. 7 in Fig. 3-5).
3.5.3 Variant 2: stack expansion backwards

Preparing the stack mounting

Fig. 3-6 Preparing the MIQ modules for stack mounting (variant 2)

1. Remove the covers from the drilled mounting holes (pos. 1 and 3 in Fig. 3-6).
2. Remove the contact cover (pos. 2).
3. Pull off the adhesive label (pos. 4).
4. On the MIQ module, remove the two countersunk screws (pos. 5) and swing open the module lid.

Mounting the contact base

Fig. 3-7 Mounting the contact base (variant 2)
Only use the plastic tapping screws supplied for attaching the contact base. They ensure the correct fit.

5 Attach the contact base (pos. 6 in Fig. 3-7) on the Universal Transmitter with the two plastic tapping screws (pos. 7).

Fig. 3-8 Premounting the ISO blind nuts (variant 2)

6 Insert the cheese-head screws (pos. 8 in Fig. 3-8) with the plastic washers in the drilled mounting holes in the module lid and loosely screw in the ISO blind nuts (pos. 9).
Attach the prepared MIQ module to the back of the Universal Transmitter. At the same time, ensure that the two clips on the Universal Transmitter click into place in the lid of the MIQ module. Subsequently, tighten the two screws (pos. 8 in Fig. 3-8).
3.5.4 Distributed mounting

General information
For the locally separated connection between Universal Transmitter and MIQ modules and between MIQ modules the following cables can be used:
- SNCIQ cable

The cables are delivered as piece goods (please specify length when ordering!).

NOTE
The IQ Sensor Net cable may be connected to the SENSORNET connections only. No wires of the cable may be connected with an external electrical potential. Otherwise, malfunctions could occur.

General installation instructions
Pay attention to the following points when connecting components via IQ SENSORNET lines:
- The sum of all IQ SENSORNET line lengths (SNCIQ, SNCIQ/UG and SACIQ) in the system may be up to a maximum of 250.
- IQ SENSORNET lines must always be installed separately at a minimum distance of 20 cm from any other lines carrying a voltage greater than 60 V.
- The terminator switch on the terminal strip of all MIQ modules in the System 182 must be set to "Off".

Materials required
- 1 x SNCIQ or SNCIQ/UG connection cable (see chapter 10 ACCESSORIES AND OPTIONS)
- Wire end sleeves for 0.75 mm² wire cross-section with matching crimping tool
- 1 x cable gland with seal (scope of delivery of MIQ module).

Tools
- Cable stripping knife
- Wire stripper

Close the MIQ module and fix it with the two countersunk screws (pos. 5 in Fig. 3-10).
Preparation of the cable ends

- Phillips screwdriver
- Small screwdriver.

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<tbody>
<tr>
<td>1</td>
<td>Cut off the cable to the required length.</td>
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<tr>
<td>2</td>
<td>Remove approx. 45 mm of cable insulation (in the case of the SNCIQ/UG earth cable, remove both the inner and outer insulation).</td>
</tr>
<tr>
<td>3</td>
<td>Only for the SNCIQ/UG earth cable: strip the outer insulation for a further 35 mm.</td>
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<tr>
<td>4</td>
<td>Shorten the exposed shielding braid up to the cable sheath.</td>
</tr>
<tr>
<td>5</td>
<td>Shorten the two fillers (plastic inlays) up to the cable sheath.</td>
</tr>
<tr>
<td>6</td>
<td>Bare the red and green wires and fit them with wire end sleeves.</td>
</tr>
<tr>
<td>7</td>
<td>Fit the filler stranded wire with a wire end sleeve.</td>
</tr>
</tbody>
</table>

Connecting the cables

The SNCIQ and SNCIQ/UG cables are connected to the terminal strip in the same way as the SACIQ sensor connection cable (see section 3.5.5):

1. Open the enclosure of the Universal Transmitter or MIQ module.
2 Select a free SENSORNET connection. At the same time, look out for the SENSORNET designation on the label on the bottom of the enclosure.

3 Screw a cable gland (pos. 1 in Fig. 3-12) with the sealing ring (pos. 2) into the enclosure.

4 Loosen the coupling ring (pos. 3 in Fig. 3-12).

5 Feed the cable through the cable gland into the enclosure.
Fig. 3-13  SENSORNET connection

6 Connect the cable ends to the terminal strip. At the same time, look out for the designations of the terminals (red / shield / green).

7 Tighten the coupling ring (pos. 3 in Fig. 3-12).

8 Close the enclosure.

The complete assignment of the terminal strip is shown in section 3.13.
3.5.5 Connecting IQ sensors

Sensors can be connected to all free SENSORNET connectors in the 182 system. The DIQ/S 182 Universal Transmitter has a SENSORNET connector. With the DIQ/JB branching module you can connect two sensors to the Universal Transmitter (see section 3.7 and installation examples in section 3.12).

General installation instructions

Observe the following points when attaching sensors to the system:

- The sum of all IQ SENSORNET line lengths (SNCIQ, SNCIQ/UG and SACIQ) in the system may be up to a maximum of 250.
- IQ SENSORNET lines must always be installed separately at a minimum distance of 20 cm from other lines that carry a voltage greater than 60 V.

Materials required

- 1 x SACIQ connection cable (see chapter 10 ACCESSORIES AND OPTIONS)
- 1 x cable gland with seal

The free end of the connection cable already has the sheath removed in the factory and all the wires are fitted with wire end sleeves.

Tools

- Phillips screwdriver
- Small screwdriver.

Connecting the SACIQ cable to the Universal Transmitter or MIQ module

The connection of the SACIQ cable to the terminal strip is described in section 3.5.4 (see CONNECTING THE CABLES, page 15).

NOTE

The SACIQ sensor connection cable may only be connected to the SENSORNET connections. No wires of the cable may be connected with an external electrical potential. Otherwise, malfunctions could occur.

Connecting the sensor to the connection cable

1. Remove the protective caps from the plug connections of the IQ sensor and SACIQ sensor connection cable and keep them safe.

2. Plug the socket of the SACIQ sensor connection cable onto the plug head connector of the IQ sensor. At the same time, rotate the socket so that the pin in the plug head connector (1) clicks into one of the two holes in the socket.

3. Then, screw the coupling ring (2) of the IQ sensor connection cable on the IQ sensor up to the stop.
For further instructions on the mounting of IQ sensors at the application location, please see the respective manuals (immersion depths, etc.).
3.6 On site mounting of the Universal Transmitter and MIQ Modules

3.6.1 General information

The DIQ/S 182 and the DIQ and MIQ modules have a comprehensive program of mounting accessories, which can be used to adapt the installation to the most varied requirements.

**NOTE**

*Components installed outside must always be protected by a sun shield against the effects of the weather (snow, ice and direct solar radiation). Otherwise, malfunctions can result. Always mount the Universal Transmitter in an upright position. Do not under any circumstances install MIQ modules without rain protection with the lid facing upwards (danger of retained humidity and penetration of moisture).*

**CAUTION**

*No contact base may be mounted on the back of the module (danger of short-circuit) if the module is mounted on a wall, a sun shield, or a top hat rail.*

**Installation options**

The most important types of installation for the Universal Transmitter are described in the following chapters:

- **Mounting on a mounting stand with the SSH/IQ sun shield:**
  The SSH/IQ sun shield provides enough space for the Universal Transmitter and two MIQ modules (section 3.6.2).

- **Mounting on the SD/K 170 sun shield**
  The SD/K 170 provides room for the Universal Transmitter. The sun shield can be mounted on round or square section pipes (e.g. rails) with the aid of the MR/SD 170 mounting kit (section 3.6.3).

- **Wall mounting:**
  The Universal Transmitter or MIQ module is permanently screwed to a wall. For wall mounting, use the WMS/IQ mounting set (see chapter 10 ACCESSORIES AND OPTIONS).

- **Panel mounting:**
  The Universal Transmitter or MIQ module is installed in the aperture of a panel. The dimensions of the aperture are 138 x 138 mm + 1 mm. The panel may not be thicker than 15 mm (section 3.6.4).

- **Top hat rail mounting:**
  The Universal Transmitter or MIQ module is mounted on a 35 mm top hat rail with the aid of a bracket, e.g. in a control cabinet. The connection can be released again with one simple movement (section 3.6.5).

The following chapters describe the mounting of the Universal Transmitter. MIQ modules are mounted in the same way.
3.6.2 Mounting on a mounting stand with the SSH/IQ sun shield

Materials required

- SSH/IQ sun shield (see chapter 10 ACCESSORIES AND OPTIONS).

Tools

- 4 mm set screw wrench
- Phillips screwdriver.

Mounting the sun shield on a mounting stand

Fig. 3-15  Mounting the SSH/IQ sun shield on a mounting stand

1 Screw the sun shield (pos. 1 in Fig. 3-15) with the four hexsocket head screws (pos. 2), the washers (pos. 3) and the clamps (pos. 4) at the required height on the mounting stand from the back.
Premounting the ISO blind nuts

Fig. 3-16 Mounting the sun shield: Premounting the ISO blind nuts

2 Remove the two countersunk screws (pos. 5 in Fig. 3-16) and swing open the lid.

3 Insert the cheese-head screws (pos. 6 in Fig. 3-16) with the plastic washers in the drilled mounting holes and loosely screw in the ISO blind nuts (pos. 7).
Mounting the Universal Transmitter on the sun shield

Position the Universal Transmitter on the sun shield and fix it into place with the two screws (pos. 6 in Fig. 3-16).

Close the lid and fix it with the two countersunk screws (pos. 5 in Fig. 3-16).
3.6.3 Mounting under the SD/K 170 sun shield

The SD/K 170 sun shield can be mounted directly on a wall, on a mounting stand or on a railing. The MR/SD 170 mounting kit is also required for mounting on a mounting stand or railing.

How to mount the sun shield at the installation location is described in the instructions for the sun shield or mounting kit.

Materials required

- SD/K 170 sun shield (see chapter 10 ACCESSORIES AND OPTIONS)
- The MR/SD 170 mounting kit is also required for mounting the sun shield on a mounting stand or railing (see chapter 10 ACCESSORIES AND OPTIONS).

Tools

- Phillips screwdriver.

Mounting the Universal Transmitter with the sun shield

Fig. 3-18 Mounting the Universal Transmitter with the SD/K 170 sun shield

1 Remove the two countersunk screws (pos. 1 in Fig. 3-18) and swing open the module lid.

2 Position the Universal Transmitter on the sun shield and fix it into place with the two screws (pos. 2 in Fig. 3-18).
3. Close the lid and fix it with the two countersunk screws (pos. 1 in Fig. 3-18).

3.6.4 Panel mounting

The space required on the panel for the Universal Transmitter is given in the dimension drawings in section 9.5.

Materials required

- PMS/IQ kit for panel mounting (see chapter 10 ACCESSORIES AND OPTIONS).

Tools

- 3 mm set screw wrench (contained in the panel installation kit).

Switch panel aperture

![Diagram of switch panel aperture with dimensions](image)

- Maximum thickness
  - 3 mm

Fig. 3-19 Mounting aperture in the switch panel (dimensions in mm)

The space required on the panel for DIQ/S 182 is given in the dimension drawings in section 9.5.
Mounting the Universal Transmitter in the panel

1. Insert the Universal Transmitter in the panel aperture from the front.

2. Slightly unscrew the screws (pos. 2 and 3) of the two angle brackets (pos. 1 in Fig. 3-20), but do not remove them.

3. Push in the two angle brackets - as shown in Fig. 3-20 - into the lateral guides of the Universal Transmitter up to the stop.

4. Tighten the screws (pos. 2).

5. Screw in the screws (pos. 3) until the screws rest snugly against the panel.
### 3.6.5 Top hat rail mounting

**Materials required**
- THS/IQ kit for top hat rail mounting (see chapter 10 ACCESSORIES AND OPTIONS).

**Tools**
- Phillips screwdriver.

**Mounting the Universal Transmitter on a top hat rail**

![Image of Universal Transmitter mounted on top hat rail]

**Fig. 3-21** Mounting the Universal Transmitter on a top hat rail

1. Screw the clamping assembly (pos. 1 in Fig. 3-21) onto the back of the Universal Transmitter with the two plastic tapping screws (pos. 2).

2. Attach the Universal Transmitter onto the top hat rail from above using the clamping assembly and press against the rail until the clamping assembly clicks into place. The Universal Transmitter can be moved sideways afterwards.

3. To unhook the Universal Transmitter, press it downward and pull it forward at the bottom.
3.7 Using DIQ modules (accessories)

The various application possibilities of the DIQ modules are shown by means of examples in section 3.12.

3.7.1 DIQ/J B

The DIQ/J B module is a passive branching module and can be used for the following purposes:

- To extend the SNCIQ(/UG) IQ SENSOR NET cable and the SACIQ sensor connection cable, e.g. to connect a sensor that is located farther away to the Universal Transmitter.
- To connect a second sensor to the DIQ/S 182 Universal Transmitter.

![DIQ/J B open](image)

Fig. 3-22 DIQ/J B open.

The DIQ/J B module has seven potential free terminals. To extend or branch lines, connect the three IQ SENSOR NET wires to each other one-to-one at any terminals:

- green <-> green
- red <-> red
- black/filler stranded wire <-> black/filler stranded wire.

3.7.2 DIQ/CHV

The DIQ/CHV module is a valve module for the automatic relay-controlled compressed air-driven cleaning function in the 182 system. It provides four additional potential free terminals to branch (extend) interface lines. For each sensor that is to have compressed air cleaning a DIQ/CHV is required.
3.7.3 Installation of the DIQ modules

The DIQ module enclosure is designed like a commercial connection socket and can be mounted directly on a wall. For mounting on a YSI mounting stand, YSI provides the MS/DIQ mounting set. It contains a pipe clip for the mounting stand and provides enough space for two DIQ modules. For assembly use the screws and blind nuts provided with the MS/DIQ as demonstrated in the following figure.

Fig. 3-24 Mounting DIQ modules with the MS/DIQ mounting set.
3.8 Electrical connections: General instructions

Cable glands

All electric cables are fed from below via prepared openings in the enclosure of the DIQ/S 182 and the MIQ modules. Cable glands with different clamping ranges are included with the DIQ/S 182 to provide sealing between the cable and enclosure as well as for strain relief. Select the matching cable gland for the respective cable diameter:

- **Small**, clamping range 4.5 to 10 mm. This cable gland is suitable for all IQ SENSORNET cables (including earth cable after stripping the outer insulation, see section 3.5.4) and IQ SENSORNET sensor connection cable.

  - sealing ring 20 x 15 x 1 mm
  - cable gland M16
  - blind plug

- **Large**, clamping range 7 to 13 mm. This cable gland is required for cable sheaths with an outside diameter of more than 10 mm and is screwed into the enclosure via an extension piece.

  - sealing ring 20 x 15 x 1 mm
  - extension piece M16/M20
  - sealing ring 24 x 19 x 2 mm
  - cable gland M20

If necessary, you can order other sizes of cable gland (see chapter 10 ACCESSORIES AND OPTIONS).
General installation instructions

Observe the following points when attaching connecting wires to the terminal strip:

- Shorten all wires to be used to the length required for the installation.
- Always fit all the ends of the wires with wire end sleeves before connecting them to the terminal strip.
- Any wires that are not used and project into the enclosure must be cut off as closely as possible to the cable gland.
- Screw a small cable gland with sealing ring into each remaining free opening and close it with a blind plug.

**WARNING**

No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that areas safe to contact could come into contact with dangerous voltages. This could result in life threatening electric shock when working with the DIQ/S 182. Always cut off any wires that are not in use as closely as possible to the cable gland.
3.9 Connecting the voltage supply

The two following paragraphs describe how to connect both models of the DIQ/S 182 Universal Transmitter to the voltage supply. How to connect additional power supply modules is described in the operating manual of the respective power supply module.

3.9.1 DIQ/S 182 (Line power version)

WARNING
If the power supply is incorrectly connected, it may represent a danger to life from electric shock. Pay attention to the following points during installation:

- The DIQ/S 182 Universal Transmitter may only be connected by a trained electrician.
- The connection of the DIQ/S 182 Universal Transmitter to the power supply may only be carried out when it is not carrying any voltage.
- The power supply must fulfill the specifications given on the nameplate and in chapter 9 TECHNICAL DATA.
- When installed in a building, a switch or power switch must be provided as an interrupt facility for the System 182.
  The interrupt facility must
  - be installed in the vicinity of the DIQ/S 182 Universal Transmitter, easily accessible by the user, and
  - be labeled as the interrupt facility for the DIQ/S 182 Universal Transmitter.
- After the DIQ/S 182 Universal Transmitter has been installed, it may only be opened if the line voltage has been switched off beforehand.

Materials required

- Wire end sleeves, suitable for the power line, with suitable crimping tool
- 1 x screwed cable gland with sealing ring (scope of delivery of the Universal Transmitter).

Tools

- Cable stripping knife
- Wire stripper
- Phillips screwdriver
- Small screwdriver.
Preparing the power cable

1. Cut off the cable to the required length.
2. Strip the cable insulation for approx. 45 mm.
3. Bare the wires of phases L and N and fit them with wire end sleeves.
4. If present, cut off the ground wire at the end of the cable sheath.

Fig. 3-25  Prepared power cable.

NOTE

The ground wire must not project into the enclosure. Otherwise, malfunctions could occur.
Connecting the power line

5 Open the enclosure of the Universal Transmitter.

6 Screw a cable gland (pos. 1 in Fig. 3-26) with sealing ring (pos. 2) into the enclosure below the power supply connection.

7 Loosen the coupling ring (pos. 3).

8 Feed the power line through the cable gland into the enclosure. When doing so bend the flexible divider (pos. 4) to the right.
WARNING
No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that areas safe to contact could come into contact with dangerous voltages. Always cut off any wires that are not in use as closely as possible to the cable gland.

11 Close the enclosure of the Universal Transmitter.
3.9.2 DIQ/S 182/24V (24 V version)

**WARNING**

If the 24 V AC/DC supply is incorrectly connected, it may represent a danger to life from electric shock. Pay attention to the following points during installation:

- The DIQ/S 182 Universal Transmitter may only be connected by a trained electrician.
- The 24 V AC/DC supply must meet the specifications quoted on the name plate and in chapter 9 TECHNICAL DATA (protective low voltage SELV).
- The connection of the DIQ/S 182 Universal Transmitter to the power supply may only be carried out when it is not carrying any voltage.
- When installed in a building, a switch or power switch must be provided as an interrupt facility for the System 182. The interrupt facility must
  - be installed in the vicinity of the DIQ/S 182 Universal Transmitter, easily accessible by the user, and
  - be labeled as the interrupt facility for the DIQ/S 182 Universal Transmitter.

Rechargeable battery systems should have a deep discharge protection. The DIQ/S 182/24V does not have any built-in deep discharge protection.

**Materials required**

- Wire end sleeves, suitable for the 24 V AC/DC feed line, with suitable crimping tool
- 1 x screwed cable gland with sealing ring (scope of delivery of the Universal Transmitter).

**Tools**

- Cable stripping knife
- Wire stripper
- Phillips screwdriver
- Small screwdriver.

**Preparing the 24 V AC/DC line**

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<tr>
<td>1</td>
<td>Cut off the cable to the required length.</td>
</tr>
<tr>
<td>2</td>
<td>Strip the cable insulation for approx. 45 mm.</td>
</tr>
<tr>
<td>3</td>
<td>Bare the wires 1 and 2 and fit them with wire end sleeves.</td>
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### Connecting the 24 V AC/DC line

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<th>Step</th>
<th>Action</th>
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<tr>
<td>4</td>
<td>Open the enclosure of the Universal Transmitter.</td>
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<tr>
<td>5</td>
<td>Screw a cable gland (pos. 1 in Fig. 3-29) with sealing ring (pos. 2) into the enclosure below the 24 V AC/DC connection.</td>
</tr>
<tr>
<td>6</td>
<td>Loosen the coupling ring (pos. 3).</td>
</tr>
<tr>
<td>7</td>
<td>Feed the 24 V AC/DC line through the cable gland into the enclosure. When doing so bend the flexible divider (pos. 4) to the right.</td>
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Fig. 3-28  Prepared 24 V AC/DC line.

Fig. 3-29  Inserting the 24V AC/DC line
Fig. 3-30  24 V AC/DC connection.

The complete assignment of the terminal strip is shown in section 3.13.

8 Connect wires 1 and 2 to the terminal strip. Make sure that the cable assignment agrees with the specification on the terminal label under the terminal strip.

9 Tighten the coupling ring (pos. 3 in Fig. 3-29).

**WARNING**

No free wires must be allowed to project into the enclosure. Otherwise there is the danger of short circuits that can cause a fire. Always cut off any wires that are not in use as closely as possible to the cable gland.

10 Close the enclosure of the Universal Transmitter.
3.10 Connections to the relay and current outputs

3.10.1 General installation instructions

WARNING
If external electrical circuits that are subject to the danger of physical contact are incorrectly connected to the relay contacts, there may be a danger of life-threatening electric shock. Electrical circuits are regarded to be subject to the danger of physical contact when there are voltages higher than the Safety Extra Low Voltage (SELV).

Pay attention to the following points during installation:

- Electrical circuits subject to the danger of physical contact must only be connected by a qualified electrician.
- Electrical circuits subject to the danger of physical contact must only be connected when they are voltage-free.
- If electrical circuits subject to the danger of physical contact are switched with a relay, no circuit that is not subject to this danger (e.g. the DIQ/CHV module) may be operated on the further relays.
- Switching voltages and switching currents on the relay contacts must not exceed the values specified in chapter 9 TECHNICAL DATA. Protect electrical circuits against currents that are too high with an electrical fuse.
- Only single-phase consumers can be switched with the relays. Under no circumstances must multiphase consumers be switched with the aid of several relays (example three-phase current driven pumps). Always switch multiphase consumers via a protective relay.
- After the Universal Transmitter has been installed, it may only be opened if all external voltages have been switched off beforehand.

Materials required

- Wire end sleeves, suitable for the connecting wires, with suitable crimping tool
- 4 x screwed cable gland with sealing ring (scope of delivery of the Universal Transmitter).

Tools

- Cable stripping knife
- Wire stripper
- Phillips screwdriver
- Small screwdriver
Connecting lines to the terminal strip

11 Open the enclosure of the Universal Transmitter.

The complete assignment of the terminal strip is shown in section 3.13.

12 Screw a cable gland (pos. 1 in Fig. 3-31) with the sealing ring (pos. 2) into the enclosure below the respective connections.

13 Loosen the coupling ring (pos. 3).

14 Feed the line through the cable gland in the enclosure.

15 Connect the wires to the terminal strip. While doing so, pay attention to the specifications on the label located under the terminal strip.

16 Tighten the coupling ring (pos. 3).

WARNING

No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that areas safe to contact could come into contact with dangerous voltages. This could result in life threatening electric shock when working with the Universal
Transmitter. Always cut off any wires that are not in use as closely as possible to the cable gland.

17 Close the enclosure of the Universal Transmitter.

3.10.2 Usage of the auxiliary voltage

The Universal Transmitter has a 24 V output (designation, HILFSSPANNUNG or AUXILIARY VOLTAGE on the terminal strip). You can use this auxiliary voltage for the relay-controlled opening of the valve in a DIQ/CHV valve module for the compressed air-driven sensor cleaning function. To do so, you have to connect the auxiliary voltage output, a free relay contact and the valve connection in the DIQ/CHV in series. Bridge a terminal of the auxiliary voltage output with a terminal of a relay output and run a control line from the remaining terminals to the valve module.

NOTE

The auxiliary voltage must not be used for other purposes.

Connection scheme for one sensor with compressed air cleaning

NOTE

Run the bridge below the divider so the bridge does not bump against the circuit board in the lid when the enclosure is closed.
Installation examples with one and two sensors with compressed air cleaning can be found in section 3.12.
3.11 Commissioning

Start checklist and system start

Before starting the system, carry out the system check using the following checklist. Always carry out the check
- before the initial commissioning
- before any further commissioning if the system has been previously extended or modified.

Start checklist

1. Are all system components correctly connected with one another (see section 3.5)?
2. Is the Universal Transmitter and all additional power supply modules correctly connected to the voltage supply (see section 3.9)?
3. Do the line voltage and line frequency agree with the data on the name plate of the Universal Transmitter and all additional power supply modules?
4. Are all IQ sensors ready for measuring, e.g. a D.O. sensor filled with electrolyte solution?

Starting the system

Switch on the voltage supply of the Universal Transmitter and all additional power supply modules. As soon as the system is successfully initialized, the measured value display appears. In the case of IQ sensors that are not yet providing measured values, "Init" appears temporarily.

Assign a name to each IQ sensor after putting it into operation for the first time so you can identify it more easily. How to assign a sensor name is described in section 5.3 on page 5-2.

If the system start failed, see chapter 8 WHAT TO DO IF ....
3.12 Installation examples

3.12.1 Connecting two sensors without compressed air cleaning

Maximum total cable length
SNCIQ(/UG) plus SACIQ = 250 m
Connection scheme of the DIQ/J B

Terminal strip DIQ/JB

SNCIQ(UG)

SACIQ

Sensor 2

Sensor 1

Shield / Filler stranded wire

Red

Green

Black

X1 X2 X3 X4 X5 X6 X7

Sensor 2

Sensor 1

Red

Green

Red

Green

Black

Black
3.12.2 Connecting two sensors with compressed air cleaning

Example:
Relay 1 controls the cleaning of sensor 1.
Relay 2 controls the cleaning of sensor 2.

Variant: Relay 1 controls the cleaning of both sensors. Cleaning of both sensors is carried out with the same settings.

**WARNING**
In this configuration, the free switching contact (here: R3) may be used to switch SELV voltages only.

**WARNING**
No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that areas safe to contact could come into contact with dangerous voltages. Always cut off any wires that are not in use as closely as possible to the cable gland.
Connection scheme of the DIQ/J B

Terminal strip DIQ/S 182

Terminal strip DIQ/CHV 1

Terminal strip DIQ/CHV 2

Variant:

Valve control line 1

Valve control line 2

Shield / Filler stranded wire

Sensor 2

Sensor 1
3.12.3 Connection of a sensor that is located at a distance (without compressed air cleaning)

Maximum total cable length SNCIQ(UG) plus SACIQ = 250 m

Connection scheme of the DIQ/J B

Terminal strip DIQ/JB

Shield / Filler stranded wire

red green red

SNCIQ(UG)

red green black

SACIQ
3.13 Figures of the terminal strips

**DIQ/S 182**

- X17: L1, X16: N
- 100...240V AC
- 100...240V DC
- Mains
- X15: +240V AC ≤ 2A AC
- X14: +240V AC ≤ 2A AC
- X13: +240V AC ≤ 2A AC
- X12: +240V AC ≤ 2A AC
- X11: +240V AC ≤ 2A AC
- X10: +240V AC ≤ 2A AC
- X9: Auxiliary voltage
- X8: 0/4...20mA
- X7: +REC-
- X6: -REC-
- X5: C2
- X4: C1
- X3: Sensornet 1
- X2: Shield
- X1: Green

**DIQ/S 182/24V**

- X17: X16
- 24V AC DC
- Input
- Power
- X15: +240V AC ≤ 2A AC
- X14: +240V AC ≤ 2A AC
- X13: +240V AC ≤ 2A AC
- X12: +240V AC ≤ 2A AC
- X11: +240V AC ≤ 2A AC
- X10: +240V AC ≤ 2A AC
- X9: Auxiliary voltage
- X8: 0/4...20mA
- X7: +REC-
- X6: -REC-
- X5: C2
- X4: C1
- X3: Sensornet 1
- X2: Shield
- X1: Green

**DIQ/J B**

- (7 passive, potential-free terminals for line extension or branching)

**DIQ/CHV**

- X6: X5: X4: X3
- X2: X1
- (Auxiliary)
- Valve
## 4 Operation

### 4.1 Operating elements

Fig. 4-1 Operating elements of the DIQ/S 182

<table>
<thead>
<tr>
<th>Key</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>m</td>
<td>Switches directly to the measured value display from all operating situations</td>
</tr>
<tr>
<td>c</td>
<td>Starts calibration of the sensor selected in the measured value display</td>
</tr>
<tr>
<td>s</td>
<td>Opens the SETTINGS menu in the measured value and status display</td>
</tr>
<tr>
<td>e</td>
<td>Switches to the higher menu level</td>
</tr>
<tr>
<td>f</td>
<td>Cancels entries without storing them</td>
</tr>
<tr>
<td>g</td>
<td>Opens the PROPERTIES menu in the measured value and status display</td>
</tr>
<tr>
<td>0</td>
<td>Confirms an entry</td>
</tr>
<tr>
<td>(toggle switch)</td>
<td>Selects:</td>
</tr>
<tr>
<td></td>
<td>- The active sensor (measured value display)</td>
</tr>
<tr>
<td></td>
<td>- Menu items</td>
</tr>
<tr>
<td></td>
<td>- List entries</td>
</tr>
<tr>
<td></td>
<td>- Letters or numerals</td>
</tr>
<tr>
<td></td>
<td>Scrolls through longer menus or texts</td>
</tr>
</tbody>
</table>
4.2 Measured value and status display

With the key you switch to the last selected measured value and status display from any operating situation. Entries that are not completed are ignored while doing so.

By pressing once again you cyclically switch between further display options.

Example:

<table>
<thead>
<tr>
<th>Sensor</th>
<th>Measured Value</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>$S02$</td>
<td>$02$ Inlet</td>
<td>$144.2$ mg/l TS</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$0.16$ mg/l O2</td>
</tr>
<tr>
<td>$S01$</td>
<td>$TS$ Inlet</td>
<td>$144.2$ mg/l TS</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$351.8$ mg/l O2</td>
</tr>
<tr>
<td>$S01$</td>
<td>$TS$ Inlet</td>
<td>$22.8$ °C</td>
</tr>
</tbody>
</table>

Operating notes

- Select a sensor in the double display with . The selected sensor is displayed in reverse video. The number and name of the selected sensor are displayed in the header. In the single display, the sensor being displayed is always the selected sensor at the same time.

- Start a calibration procedure for the selected sensor with . Starting a calibration procedure from the display of interfaces is not possible.
Select the PROPERTIES menu with \(\text{OK}\). With this menu you can put sensors in the maintenance condition and prompt important data (calibration data, error messages, operating states, software versions, etc.).

Open the SETTINGS menu with \(\text{S}\).

The following displays inform you of special states of sensors:

<table>
<thead>
<tr>
<th>Condition</th>
<th>Description</th>
</tr>
</thead>
</table>
| Init      | Sensor is being initialized  
- during commissioning  
- if a new IQ sensor is recognized that is not yet giving measured values |
| ----      | Sensor inactive or inadmissible operating conditions |
| Cal       | Sensor is being calibrated |
| Clean     | Cleaning procedure active |
| Error     | No communication with the sensor due to defective connection |
| OFL       | Measuring range undercut or exceeded (overflow) |
| Display flashes | Sensor in maintenance condition |

If the info symbol \(\text{i}\) or error symbol \(\text{h}\) appears in the header, error messages from the sensors or error conditions of the system have occurred. Error messages from the sensors are entered in the log book. The log book is described in detail in section 4.4.3. Error conditions of the system can e.g. be an insufficient operational voltage or malfunctions of the communication and are displayed in the PROPERTIES / SYSTEM STATUS menu (see section 4.4.1).
4.3 Working with the SETTINGS menu

All settings in the SETTINGS menu can be protected by a password against unauthorized changing. For more detailed information on password protection, see section 4.6.

4.3.1 Selection menus

Pressing \(\text{S}\) switches from the measured value display to the SETTINGS menu (main menu).

![SETTINGS menu](image)

Operating notes:

- In the main menu, the lock symbol shows the current safety level for the settings.
  - \(\text{S}\) Settings not protected by password
  - \(\text{L}\) Settings protected by password (reading possible only)

For more detailed information on password protection, see section 4.6.

- The arrows \(\uparrow/\downarrow\) appear automatically if further display contents are above or below the visible display range.

- With the toggle switch \(\text{w}\) you highlight a menu item (displayed in reverse video) and move the visible display range up or down.

- To open a menu item, highlight it and press \(\text{g}\). The display switches to a further submenu or to a setting table.

- To return to the measured value display, press \(\text{m}\) or \(\text{e}\).
4.3.2 Setting tables

In the setting tables, you make the actual settings. Two lines together represent each setting. The name of the setting is in the upper line on the left side of the display. The corresponding value is in the line below on the right side.

Fig. 4-3 Example of a setting table

Operating notes

- The arrows ↑/↓ appear if further display settings are above or below the visible display range.
- With the toggle switch you highlight a setting (displayed in reverse video) and move the visible display range up or down.
- To edit a setting highlight it and press OK. The line below is highlighted and switches to the entry mode. Depending on the operating situation, a new submenu or a table with further relevant settings can open up.
- Break off an action and change to the next higher level with the key.
- Move directly to the measured value display with M.

To accept all settings, you have to highlight the Save and quit menu item at the lower end of the setting table and press OK. If you exit the setting table via M, Esc/Quit or the Quit menu item, all changes are ignored.

Fig. 4-4 Save and quit
4.3.3 Entry mode

In the entry mode, you can change individual values or enter a character string. Depending on the value type, change a value as follows:

- **Fixed values of a selection list** (e.g. sensor measuring ranges):
  This is the most frequent form of an entry. Select the required option with the toggle switch (ﬁ) and confirm the selection with (✓). The display switches back to the setting table.

  ![Example of a selection list](image)

- **Character strings** (text and numerals):
  The following letters, numerals and special characters can be entered: AaBb..Zz0..9µ%&/()+-=><!?_°.

  Entries are made character after character. Select the first character with the toggle switch (ﬁ) and press (✓). The entry mark moves to the next position and indicates (ﬁ). Select the next character with the toggle switch (ﬁ). When you have selected the required sequence of characters select (ﬁ) as the following character and press (✓). The entry is completed with this and the display switches back to the setting table.

  ![Example of text entry](image)

  If you want to correct a previously selected character while entering, select the thin arrow to the left (←) and press (✓). This moves the entry mark by one digit to the left. Thus you can go back to the required character. All characters on its right side, however, have to be entered once again.

  If you want to restart entering the characters, select the thick arrow to the left (←) and press (✓).
● **Numerals:**
Entering numerals is made in the same way as entering characters.
The following numerals can be entered: 0 . . 9 −.
Entering "−" or "." is only allowed where it makes sense, e.g. "−" at
the first position only.

**Save and quit**
On principle, all settings done in the entry mode are only taken over
after you selected the Save and quit item in the relevant setting table
and pressed OK. If you exit the setting table via M, Q or the Quit
menu item, all changes are ignored.
Exceptions: Date/time, air pressure and password.
4.4  PROPERTIES menu

4.4.1  Overview

Pressing \( \times \) switches from the measured value display to the PROPERTIES menu.

In the PROPERTIES menu, you can prompt calibration data and various information on system components. Moreover, you can switch on and off the maintenance condition of a sensor.

<table>
<thead>
<tr>
<th>PROPERTIES</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maintenance Sensor ( Sxx )</td>
</tr>
<tr>
<td>Sensor status ( S01 )</td>
</tr>
<tr>
<td>System status</td>
</tr>
<tr>
<td>List of components</td>
</tr>
</tbody>
</table>

Fig. 4-7  PROPERTIES menu

Submenus/functions

- **Maintenance Sensor \( Sxx \)**: With this function, you switch on and off the maintenance condition of a sensor (see section 4.4.2).

- **Sensor status \( Sxx \)**
  Here you can prompt the following data of a sensor (see section 4.4.3):
  - Type, series number and software version
  - Data of the last calibration
  - Error and info messages

- **System status**
  Here you can prompt the following data of the system:
  - Series number and software version of the Universal Transmitter
  - Status of the operational voltage (\( \square = \text{OK} / \square = \text{faulty} \))
  - Status of communication (\( \square = \text{OK} / \square = \text{faulty} \))
  - Current states of interfaces

If the operational voltage or communication are faulty, the flashing error symbol \( \triangle \) appears in the header of the measured value display. The error symbol \( \triangle \) automatically disappears when the malfunction has been eliminated.

- **List of components**
  Here is a list of all connected sensors.
### 4.4.2 Maintenance condition

When an IQ sensor is calibrated, cleaned, serviced or repaired, the maintenance condition for the relevant IQ sensor should always be switched on.

In the maintenance condition
- apart from the measured value display, the system does not react to the current measured value or the condition of the selected IQ sensor
- IQ sensor errors do not prompt changes in the conditions of linked outputs.

The following diagram gives you an overview of when an IQ sensor is in the maintenance condition.
**Recommended proceeding for cleaning, maintenance and repair**

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Switch on the maintenance condition for the IQ sensor. The measured value display flashes.</td>
</tr>
<tr>
<td>2</td>
<td>Pull the sensor out of the sample.</td>
</tr>
<tr>
<td>3</td>
<td>Carry out the cleaning, maintenance or repair (removal and replacement) of the sensor.</td>
</tr>
<tr>
<td>4</td>
<td>Submerse the sensor in the sample again.</td>
</tr>
<tr>
<td>5</td>
<td>Wait until the measured value does no longer change.</td>
</tr>
<tr>
<td>6</td>
<td>Switch off the maintenance condition for the sensor. The display of the sensor in the measured value display does no longer flash.</td>
</tr>
</tbody>
</table>

**Automatic switch-on of the maintenance condition**

The maintenance condition for IQ sensors is automatically activated
- during calibration. After calibration the IQ sensor remains in the maintenance condition until the maintenance condition is switched off manually (see section 4.5)
- during a compressed-air cleaning cycle. After the cleaning cycle is finished the maintenance condition is automatically switched off again.
4.4.3  Sensor status Sxx

In the SENSOR STATUS Sxx menu you can prompt the following information on a sensor:

- Type and series number
- Software status
- Error and info messages ("log book")
- Data of the last calibration (only for sensors that can be calibrated)

![STATUS SENSOR S01](image)

**Log book**

The log book is a list of messages related to a sensor. If there is a new message the info or error symbol in the header of the measured value display flashes:

- △ Flashes if a new or unacknowledged error message is present in the log book that requires immediate action.
- ① Flashes if a new or unacknowledged informational message is present in the log book.

If there are info and error messages present at the same time, the error symbol △ flashes (more important).

The flashing of the info or error symbol only stops after all detailed message texts in the log book have been opened and marked with a tick (✔). The operating sequence to do this is described on page 4-13.

The error symbol also flashes if the operational voltage or communication in the system are faulty. You can check this in the PROPERTIES / SYSTEM STATUS menu (see section 4.4.1).
Calibration data

You can view the data of the last calibration under the Cal menu item. Sensors that have not yet been calibrated do not have this menu item. The symbol in the Cal line quotes the validity state:

😊 = valid
’n’ = invalid

The content and form of the calibration data depend on the sensor type.

Log book messages

Each log book message in the log book consists of one line. The latest message is on the first position. They are not yet marked with a tick, i.e. acknowledged.

![Log book example](image)

<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Message type (error or info symbol) of an unacknowledged message, or tick (✓) with an acknowledged message</td>
<td>Message code</td>
<td>Date and time of the message</td>
</tr>
</tbody>
</table>

The log book shows the current status at the point of time it was opened. If new messages arrive while the log book is open, these do not appear in the log book. The new messages are only included when you switch to the measured value and status display.
Structure of the message code

Fig. 4-10  Message code

<table>
<thead>
<tr>
<th>Pos.</th>
<th>Information</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Category</td>
<td>• Info message (I)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Error message (E)</td>
</tr>
<tr>
<td>2</td>
<td>Type</td>
<td>• Calibration (C)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Installation and commissioning (I)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Instructions for service and repair (S)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Application instructions (A)</td>
</tr>
<tr>
<td>3</td>
<td>Type number</td>
<td>Each type contains subtypes (0..9A..Z)</td>
</tr>
</tbody>
</table>

Only the last message of each message code is ever displayed. If a new message arrives with a message code that already exists in the log book, the older message is overwritten.

Detailed message text

You can view the detailed message text when you acknowledge the message. It contains a precise description of the message codes and, if required, instructions for any further actions. The detailed message texts can also be found in the respective sensor operating manual.

Proceeding:
Open log book, acknowledge messages and view detailed messages

1  Open the PROPERTIES menu. To do so, press \( \text{OK} \) in the measured value display.

2  Select Sensor status Sxx (xx = required sensor) and press \( \text{OK} \).
Select the Log... menu item and press \( \text{OK} \). The log book is displayed.

Highlight the message to be acknowledged and press \( \text{OK} \). The detailed message text is displayed. Scroll through the text with the toggle switch \( \downarrow \).

Press \( \text{OK} \). Thus you acknowledge the message (✓).

Press \( \text{OK} \) once again. With this you return to the log book and can view and acknowledge further messages as necessary.

To exit the log book press \( \text{ESC} \). Return directly to the measured value and status display with \( \text{M} \).
4.5 Calibration of sensors

Sensors can be protected by a password against unauthorized calibration. For more detailed information on password protection, see section 4.6.

General proceeding

1. Switch to the measured value display with \( M \).
2. Select the sensor to be calibrated with \( W \) (in the single display, the sensor being displayed is always selected at the same time).
3. Call up calibration with \( C \). The message, During the calibration procedure, the linked outputs are frozen, appears. The maintenance condition is switched on the next time the \( G \) key is pressed. Return to the measured value display without switching on the maintenance condition with \( M \) or \( E \).

By activating the maintenance condition, linked outputs remain in their present state. The measured value or status display of the sensor flashes in the measured value display.

4. Confirm with \( G \). The maintenance condition is active.

The following proceeding is sensor type specific. The display guides you through all steps. Exactly follow the instructions. A message of the success of the calibration and the determined calibration data appear at the end.

Up to this point you can cancel the calibration procedure with the \( E \) key at any time. The system continues to work with the old calibration data. The maintenance condition, however, has to be switched off again in any case.
5 Confirm the calibration data with \( \text{OK} \). Calibration is completed with this. The following display message describes the further steps to put the sensor into operation again.

<table>
<thead>
<tr>
<th>Operation System 182</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>S02 CALIBRATE</strong></td>
</tr>
<tr>
<td><strong>After calibration:</strong></td>
</tr>
<tr>
<td>* Submerge sensor</td>
</tr>
<tr>
<td>in sample</td>
</tr>
<tr>
<td>* When meas val. is **</td>
</tr>
</tbody>
</table>

6 Confirm with \( \text{OK} \). The display returns to the measured value display (the measured value flashes as the sensor is still in the maintenance condition).

7 If calibration was successful, immerse the sensor in the test sample.

8 Wait for a stable measured value.

9 Switch off the maintenance condition (highlight sensor and press \( \text{OK} \) three times). The measured value has stopped flashing.

If calibration was not successful, this is indicated by "----" on the display and a corresponding message with remedial actions appears in the log book. Follow the instructions and repeat calibration.
4.6 Passwords

You can assign and activate two passwords for the System 182.

- **Settings password**
  protects all settings in the SETTINGS menu.
  If the password is active, all settings can be viewed but not changed.
  The password query appears on leaving a setting table with the Save and quit command. Resetting the system configuration to default is also protected.

- **Calibration password**
  protects against unauthorized calibration.
  If this password is active, the password query appears on calling up calibration with . If no valid password is entered, calibration is blocked.

**Configuring passwords**

Activating/deactivating and changing passwords is done in the SETTINGS -> System menu.

```
SYSTEM SETTINGS
Date/Time
Pressure/Altitude
Settings  Zugriffsbeschränkung
Calibrate  Zugriffsbeschränkung
```

**Fig. 4-11 SYSTEM SETTINGS menu**

**Operating notes**

- The settings password is configured with the Settings / menu item.
- The calibration password is configured with the Calibrate / menu item.
- Any activating, deactivating or changing action requires the entry of the relevant current password.
5 The SETTINGS menu

5.1 Overview of the SETTINGS menu

Pressing $ switches from the measured value display to the SETTINGS menu (main menu).

![Fig. 5-1 Submenus in the SETTINGS menu](image)

The individual submenus are described in the following paragraphs.

5.2 Language

In this menu, you can set the system language.

**Proceeding: selecting the language**

1. Open the SETTINGS menu with $.
2. Select and confirm the Language menu item with $ and OK. The LANGUAGE display opens.
3. Select the required language from the list with $ and confirm with OK. The selection is taken over immediately. The display switches to the higher menu level.
4. Switch to the measured value display with OK.
5.3 Sensor S01/S02

In this menu, you can assign a name of your choice to a sensor and adjust the sensor so it optimally meets the requirements of your application (measured parameter, measuring range, etc.).

All settings are specific for the respective sensor type. They can only be modified if the sensor is connected and communicates with the Universal Transmitter properly. Otherwise, the dataset is inactive. How to deal with inactive datasets is described below.

General steps for editing sensor settings are given below. The Sensorname menu item is always on the first position of the setting table. Details of further sensor settings can be found in the chapter, COMMISSIONING of the sensor operating manual.

Proceeding: carrying out settings

5  Open the SETTINGS menu with .

6  Using and Sensor, select and confirm the S0x menu item (corresponding to sensor 1 or sensor 2).

   The following note appears:
   If the measuring mode or measuring range is changed, the links of the sensor are erased.

7  If you want to continue press .
   The setting table of the sensor is displayed.

8  Edit the setting table as described in section 4.3.2.
An inactive dataset for an IQ sensor arises if the Universal Transmitter receives no signals from an already registered IQ sensor. The Error display appears on the measured value display instead of a measured value.

An inactive dataset can be reactivated by assigning it, e.g. to an IQ sensor of the same type (see section 8.3.2). All settings are retained. If you no longer require these data, you can erase them. All the settings belonging to this IQ sensor as well as any links with outputs are deleted by this action.

**Proceeding: deleting inactive datasets**

1. Open the SETTINGS menu with $S$.

2. Using $\uparrow$ and $\rightarrow$, select and confirm the Sensor S0x menu item (corresponding to sensor 1 or sensor 2).
   - If the dataset is inactive the following display appears:

   ![DELETE SENSOR DATA](image)

   - Select Delete dataset with $\downarrow$ and confirm with $\rightarrow$.
     - The dialog window for the security prompt appears.

3. Select Delete dataset with $\downarrow$ and confirm with $\rightarrow$.

4. Select Delete dataset with $\downarrow$ and confirm with $\rightarrow$.
   - The inactive sensor is erased.

**5.4 Relay output R1/R2/R3, mA output C1/C2**

In both menus you can link sensors with the relay and current outputs of the Universal Transmitter and adjust the outputs. The various setting options are described in detail in the chapter 6 OUTPUTS menu.
5.5 System

The settings in the SYSTEM menu comprise:

- **Date/Time**

- **Pressure/Altitude**
  This setting is important if you want to carry out D.O. measurements with the System 182.
  (adjustable range: 500 ... 1100 mbar or 0 ... 5955 m altitude).

- **Settings / /**
  Here you can configure the password for the settings.
  For details on the passwords refer to section 4.6.

- **Calibrate / /**
  Here you can configure the password for calibration.
  For details on the passwords refer to section 4.6.

- **Display contrast**
  Here you can set the display contrast for optimum readability.

- **Delivery state**
  Here you can reset all settings to default. Only the date, time and contrast setting for the display will remain stored. If the settings password is active, a password prompt appears before the reset. In any case a security prompt appears to prevent an inadvertent reset.

### Delivery condition

<table>
<thead>
<tr>
<th><strong>Settings</strong></th>
<th><strong>Default values</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>Language</td>
<td>English</td>
</tr>
<tr>
<td>Pressure/Altitude</td>
<td>1013 mbar / 0 m</td>
</tr>
<tr>
<td>Settings password</td>
<td>1000 / inactive</td>
</tr>
<tr>
<td>Calibration password</td>
<td>1000 / inactive</td>
</tr>
<tr>
<td>Sensor settings</td>
<td>Sensor dependent (see settings tables in the respective sensor operating manual). Note: Calibration of the sensor is stored in the sensor and is retained when the system configuration is reset.</td>
</tr>
<tr>
<td>Relay outputs</td>
<td>no function, all links are erased</td>
</tr>
<tr>
<td>Current outputs</td>
<td>no function, all links are erased</td>
</tr>
</tbody>
</table>
6 Outputs

6.1 Outputs of the DIQ/S 182

The DIQ/S 182 Universal Transmitter has three relays outputs and two current outputs.

**Functions for relay outputs**
- System monitoring
- Sensor monitoring
- Limit indicator
- Frequency controller
- Pulse-width output
- Sensor controlled
- Cleaning
- Manual control

Relay outputs can be configured as opener or closer.

**Functions for current outputs**
- Recorder
- PID controller
- Fixed current value

You can view the current states of the relay and current outputs in the measured value and status display (see section 4.2).

**Valve outputs (MIQ/CHV PLUS)**

The MIQ/CHV PLUS valve module is administrated by the system as a valve output (designation, MIQ/CHV PLUS V1). The relevant setting tables are available via the SETTINGS menu.

The installation and settings of the valve module are described in the operating manual of the MIQ/CHV PLUS.
6.2 Linking and adjusting: general proceedings

6.2.1 Linking outputs

Linking options
You have the following options of linking outputs:

- Sensor S01
  The output is linked with sensor 01

- Sensor S01
  The output is linked with sensor 02

- Sensor S01&S02
  The output is linked to both sensors S01 and S02.
  This option is available for relay outputs only.

- System
  Select this option if you want to use the output for system monitoring
  (details, see section 6.4.2).

Proceeding: linking outputs
Proceed as follows if the output was not yet linked. If you want to change a link you have to erase the existing link first.

1. Open the SETTINGS menu with S.

2. Using ← and →, select and confirm the Relay output Rx menu item (corresponding to relay 1, 2 or 3) or mA output Cy (corresponding to current output 1 or 2). A list with all linking options is displayed.

3. Select the required option with ← and confirm with →.
   The output is linked. The link is displayed in the header when the setting of the output is edited.
### 6.2.2 Deleting a link with an output

If you no longer need a link you can erase the link.

**Proceeding: erasing a link**

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Open the SETTINGS menu with $S$.</td>
</tr>
<tr>
<td>2</td>
<td>Using ( \uparrow ) and ( \downarrow ), select and confirm the Relay output Rx menu item (corresponding to relay 1, 2 or 3) or mA output Cy (corresponding to current output 1 or 2).</td>
</tr>
<tr>
<td>3</td>
<td>Using ( \uparrow ), select Delete link and confirm with ( \times ). A security prompt appears.</td>
</tr>
<tr>
<td>4</td>
<td>Using ( \uparrow ), select Delete link and confirm with ( \times ). The link is deleted.</td>
</tr>
</tbody>
</table>
6.2.3 Setting outputs

Proceeding: setting an output

1. Open the SETTINGS menu with \( \text{[5]} \).

2. Using \( \text{[4]} \) and \( \text{[5]} \), select and confirm the Relay output Rx menu item (corresponding to relay 1, 2 or 3) or mA output Cy (corresponding to current output 1 or 2).

<table>
<thead>
<tr>
<th>R1-S02 SETTINGS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Relay function</td>
</tr>
<tr>
<td>Limit indicator</td>
</tr>
<tr>
<td>Measured variable</td>
</tr>
<tr>
<td>Main variable</td>
</tr>
</tbody>
</table>

3. Confirm the selection Set output with \( \text{[5]} \). The setting table of the output is displayed.

4. Edit the setting table as described in section 4.3.2.

To accept all settings, you have to highlight the Save and quit menu item at the lower end of the setting table and press \( \text{[5]} \). If you exit the setting table via \( \text{[4]} \), \( \text{[5]} \)/Quit or the Quit menu item, all changes are ignored.
6.3 Basic information on relay functions

In this chapter, you will find general basic information concerning the following relay functions:

- Monitoring (see section 6.3.1)
- Limit indicator (see section 6.3.2)
- Proportional output (see section 6.3.3)

6.3.1 Monitoring

When using a relay for monitoring, a relay action (Open, Close) occurs when certain states occur. This function is suitable, e.g. for the monitoring of errors in the system.

For monitoring functions, use the relay preferably as an opener. In the case of an error, the relay opens. As a result, the monitoring function operates even if, e.g. the supply voltage fails.

6.3.2 Limit indicator

With a limit indicator, a relay switches when a specified limiting value is exceeded or undercut.

Limit indicators can be used in the following way:

- Monitoring a limiting value using a relay: when a limiting value (upper or lower limiting value) is exceeded or undercut, a relay switches. The Open or Close relay actions are possible in each case (see page 6-6).
- Monitoring two limiting values using two relays: if the upper limiting value is exceeded or undercut, a relay switches, and if the lower limiting value is exceeded or undercut, another relay switches. The Open or Close relay actions are possible in each case (see page 6-6).

If the simple monitoring function (Open, Close) with one or two relays is not sufficient, use proportional output (see section 6.3.3).
Monitoring limiting values using one or two relays

Fig. 6-1  Switching points for relays with the function of a limit indicator

1 Upper limit value (relay 1) exceeded
2 Selected switching delay t₁ for relay 1 expired
   Relay 1 switches
3 Hysteresis for upper limiting value (relay 1) undercut
4 Selected switching delay t₁ for relay 1 expired
   Relay 1 switches back
5 Lower limit value (relay 2) undercut
   Selected switching delay t₂ for relay 2 expired
   Relay 2 switches
6 Hysteresis for lower limiting value (relay 2) exceeded
   Selected switching delay t₂ for relay 2 expired
   Relay 2 switches back

A switching delay (t) can be set up for each relay for switching processes. This is the time period for which a limiting value must be exceeded before the relay switches. This prevents frequent switching if the measured values are close to the limiting value.
6.3.3 Proportional output

In the case of proportional output, a relay switches cyclically on and off in a defined measured value range (proportional range). At the same time, the relay switches with a:

- duration of operation that corresponds to the measured value (pulse-width output, see page 6-9) or
- switching frequency (frequency output, see page 6-10).

Proportional outputs can be used in the following way:

- Output with one relay:
  An output range is defined with a Start value and an End value. No output takes place above and below the output range (see page 6-8).

- Output with two relays:
  An output range is defined for each relay with a Start value and an End value. One relay outputs in the upper output range and a further relay in the lower output range (see page 6-8).
**Output with one relay**

Switching frequency $f$ or Pulse width $v$

![Graph showing proportional band with measured value and relay 1 and 2](image)

**Output with two relays**

Switching frequency $f$ or Pulse width $v$

![Graph showing proportional bands with measured value and relays 1 and 2](image)

1. **Start value**
   Measured value with a minimum pulse width or switching frequency

2. **End value**
   Measured value with a maximum pulse width or switching frequency
Pulse width output

The output via the pulse width is used, e.g. for controlling valves.

Pulse-width regulation changes the duration of operation (t_{on}) of the output signal. Depending on the position of the measured value in the proportional range, the relay is operated for a longer or shorter period.

\[ v = \left( \frac{t_{on}}{T} \right) \times 100\% \]

\[ v = \text{pulse width}, \ T = \text{cycle duration}, \ t_{on} = \text{turn-on duration} \]

- If the measured value is at the end of the proportional range (End value), the turn-on duration (t_{on}) is long, the turn-off duration is short. This means the relay operates for a longer period.
- If the measured value is at the beginning of the proportional range (Start value), the turn-on duration (t_{on}) is short, and the relay operates for a correspondingly shorter period.

If the duration of the closing or opening pulse is shorter than 0.1 s, the relay remains open or closed for the complete cycle duration.
**Frequency output**  
Switching frequency output is used, e.g. for controlling dosing pumps.

In contrast to the pulse-width output, not the pulse width is modulated with frequency output but the switching frequency of the output signal. Depending on the position of the measured value in the proportional range, the relay is switched more often or less often.

While the selected switching duration \( t_{on} = 0.3 \text{ s} \) always remains constant, the switching frequency at which the relay switches changes depending on the measured value.

- If the measured value is at the end of the proportional range (End value), the switching frequency is higher.
- If the measured value is at the beginning of the proportional range (Start value), the switching frequency is low.
**Characteristic curves**

Through the selection of the Start value and End value, the proportional output can be operated with a positive or negative characteristic curve.

- **Positive characteristic curve:**
  Select the End value to be greater than the Start value.
  The turn-on duration or frequency increases with an increasing measured value (see page 6-12).

- **Negative characteristic curve:**
  Select the End value to be smaller than the Start value.
  The turn-on duration or frequency decreases with an increasing measured value (see page 6-13).

The maximum values for the pulse width or switching frequency are assigned to the End value and the minimum values for turn-on duration or frequency are assigned to the Start value.

---

![Positive characteristic curve](image1)

**Fig. 6-6**  Positive characteristic curve

![Negative characteristic curve](image2)

**Fig. 6-7**  Negative characteristic curve
Positive characteristic curve

The proportional output range begins above the initial value. If the proportional range is undercut or exceeded, the selected behavior comes into force.

**Fig. 6-8 Pulse width output**

**Fig. 6-9 Frequency output**

<table>
<thead>
<tr>
<th></th>
<th>Start value</th>
<th>End value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Measured value with a minimum pulse width or switching frequency</td>
<td>Measured value with a maximum pulse width or switching frequency</td>
</tr>
</tbody>
</table>
**Negative characteristic curve**

The proportional output range begins below the initial value. If the proportional range is undercut or exceeded, the selected behavior comes into force.

---

**Fig. 6-10  Pulse width output**

- Start value
  - Measured value with a minimum pulse width or switching frequency

- End value
  - Measured value with a maximum pulse width or switching frequency

**Fig. 6-11  Frequency output**
6.4 Setting table for relays

6.4.1 Functions and settings

To set a relay its function has to be selected first. Then the relevant setting table is displayed:

<table>
<thead>
<tr>
<th>Function</th>
<th>Setting table</th>
</tr>
</thead>
<tbody>
<tr>
<td>No function</td>
<td>The relay output is not used.</td>
</tr>
<tr>
<td>System monitoring</td>
<td>see section 6.4.2</td>
</tr>
<tr>
<td>Sensor monitoring</td>
<td>see section 6.4.3</td>
</tr>
<tr>
<td>Limit indicator</td>
<td>see section 6.4.4</td>
</tr>
<tr>
<td>Frequency controller</td>
<td>see section 6.4.5</td>
</tr>
<tr>
<td>Pulse-width output</td>
<td>see section 6.4.6</td>
</tr>
<tr>
<td>Sensor controlled</td>
<td>see section 6.4.7</td>
</tr>
<tr>
<td>Cleaning</td>
<td>see section 6.4.8</td>
</tr>
<tr>
<td>Manual control</td>
<td>see section 6.4.9</td>
</tr>
</tbody>
</table>
6.4.2 **System monitoring**

**Function**
The System monitoring enables monitoring system errors.

To set up the System monitoring function for a relay output you have to select the System option when linking the relay output (see section 6.2.1).

It can be used to monitor the following system errors:

<table>
<thead>
<tr>
<th>Settings</th>
<th>Selection</th>
<th>Explanations</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power failure</td>
<td>On/Off</td>
<td>The Power failure On/Off function monitors the supply voltage in the DIQ/S 182. If the voltage falls below a critical value, the relay switches.</td>
</tr>
<tr>
<td>Collective error</td>
<td>On/Off</td>
<td>The Collective error On/Off function simultaneously monitors the proper function of all sensors. (for details see below this table)</td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>For all functions of the System monitoring, the relay action is set to Open.</td>
</tr>
</tbody>
</table>

**Collective error message**

In the case of a Collective error message, the relay opens if one of the following malfunctions occurs:

- One of the sensors properly registered at the controller does not supply a valid main measured value
- One of the sensors properly registered at the controller does not supply a valid secondary measured value

In any case, the relay remains open for 10 seconds and only closes when the malfunction is no longer present.

In the following cases, the relay does **not** open despite an invalid measured value:

- The sensor is being calibrated
- The sensor is in the maintenance condition
- The sensor is being cleaned with the aid of a valve module in the system (compressed air operated cleaning system).
6.4.3 **Sensor monitoring**

**Function**

The Sensor monitoring function enables to monitor sensor errors and the maintenance condition.

In order to set up the Sensor monitoring function for a relay output, the relay output must be linked with a sensor (see section 6.2.1).

**Settings**

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Errors</td>
<td>All</td>
<td>All sensor errors (special ones and general ones) are monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>Special</td>
<td>Special sensor errors are monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>Off</td>
<td>Sensor errors are not monitored.</td>
</tr>
<tr>
<td>Mainten. Condition</td>
<td>On</td>
<td>Switching on and off the maintenance condition is monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>Off</td>
<td></td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>For all functions of the Sensor monitoring, the relay action is set to Open.</td>
</tr>
</tbody>
</table>

Preferably set up the relay output as an opener for monitoring functions.

**Special sensor errors**

The special sensor errors are sensor-dependent. Details of this are given in the component operating manual of the respective sensor.

<table>
<thead>
<tr>
<th>Init</th>
<th>can prompt a relay action for a short time, depending on the starting behavior of the system</th>
</tr>
</thead>
<tbody>
<tr>
<td>----</td>
<td>Invalid measured value, or defective sensor</td>
</tr>
<tr>
<td>Error</td>
<td>Communication with sensor interrupted</td>
</tr>
<tr>
<td>OFL</td>
<td>Measuring range undercut or exceeded (overflow)</td>
</tr>
</tbody>
</table>
6.4.4 Limit indicator

The characteristic of the limit indicator is laid down in the Limit value UL, Limit value LL, Hysteresis UL and Hysteresis LL settings. The fundamentals of the function are described in the introductory chapter (see section 6.3.2).

In order to set up the Limit indicator function for a relay output, the relay output must be linked with a sensor (see section 6.2.1).

### Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limit values</td>
<td>UL main variable, LL main variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td></td>
<td>UL adjoining var., LL adjoining var.</td>
<td></td>
</tr>
<tr>
<td>Limit value UL</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Any upper or lower limiting value</td>
</tr>
<tr>
<td>Limit value LL</td>
<td>0 - 10 % of the measuring range</td>
<td>Hysteresis for upper or lower limiting value</td>
</tr>
<tr>
<td>Hysteresis UL</td>
<td>0 - 10 % of the measuring range</td>
<td>Hysteresis for upper or lower limiting value</td>
</tr>
<tr>
<td>Hysteresis LL</td>
<td>0 - 10 % of the measuring range</td>
<td>Hysteresis for upper or lower limiting value</td>
</tr>
<tr>
<td>Behavior at error</td>
<td>Open, Close, Unchanged</td>
<td>The relay opens, closes, or remains unchanged in case of system errors or sensor errors (see page 6-33).</td>
</tr>
<tr>
<td>Action</td>
<td>Open, Close</td>
<td>Relay action</td>
</tr>
<tr>
<td>Switching delay</td>
<td>0 ... 3600 s</td>
<td>The time period for which a limiting value must be exceeded before the relay operates. Prevents frequent switching for measured values that are close to the limiting value.</td>
</tr>
</tbody>
</table>
6.4.5 Frequency controller

Function

The characteristic of the frequency output is laid down in the Start value, End value, Frequency (f) min. and Frequency (f) max. settings. The fundamentals of the function are described in the introductory chapter (see section 6.3.3).

In order to set up the Frequency controller function for a relay output, the relay output must be linked with a sensor (see section 6.2.1).

Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.).</td>
</tr>
<tr>
<td></td>
<td>Adjoining variable</td>
<td>Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Start value</td>
<td>within the</td>
<td>Minimum spacing: 5 % of the measuring range</td>
</tr>
<tr>
<td></td>
<td>measuring range</td>
<td></td>
</tr>
<tr>
<td></td>
<td>(sensor-dependent)</td>
<td></td>
</tr>
<tr>
<td>End value</td>
<td>0 to 120 1/min</td>
<td>Minimum spacing: 10 1/min</td>
</tr>
<tr>
<td>Frequency (f) min.</td>
<td>0 to 120 1/min</td>
<td>In case of system errors or sensor errors (see page 6-33), the relay switches with the frequency specified.</td>
</tr>
<tr>
<td>Frequency (f) max.</td>
<td>0 to 120 1/min</td>
<td></td>
</tr>
<tr>
<td>Frequency with error</td>
<td>0 to 120 1/min</td>
<td></td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>Relay action</td>
</tr>
<tr>
<td></td>
<td>Close</td>
<td></td>
</tr>
</tbody>
</table>

Characteristic curve

If a value is entered for End value that is greater than the Start value, the output has a positive characteristic curve.

In order to obtain a negative characteristic curve, a value must be entered for End value that is smaller than the value for Start value.
6.4.6 Pulse-width output

Function

The characteristic of the pulse width output is laid down in the Start value, End value, Pulse width (v) min. and Pulse width (v) max. settings. The fundamentals of the function are described in the introductory chapter (see section 6.3.3).

In order to set up the Pulse-width output function for a relay output, the relay output must be linked with a sensor (see section 6.2.1).

Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td></td>
<td>Adjoining variable</td>
<td></td>
</tr>
<tr>
<td>Start value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Minimum spacing: 5 % of the measuring range</td>
</tr>
<tr>
<td>End value</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Pulse width (v) min.</td>
<td>0 ... 100 %</td>
<td>Minimum spacing: 10 % of the Cycle duration (T)</td>
</tr>
<tr>
<td>Pulse width (v) max.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Cycle duration (T)</td>
<td>5 ... 100 s</td>
<td>Length of the switching period ( T = (t_{on} + t_{off}) )</td>
</tr>
<tr>
<td>Error pulse width</td>
<td>0 ... 100 %</td>
<td>In case of system errors or sensor errors (see page 6-33), the relay switches with the pulse-width specified.</td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>Relay action</td>
</tr>
<tr>
<td></td>
<td>Close</td>
<td></td>
</tr>
</tbody>
</table>

Characteristic curve

You can specify the minimum and maximum pulse width (v). This determines the steepness of the characteristic curve of the output.
6.4.7 **Sensor controlled**

With the Sensor controlled function, the relay is controlled by a linked sensor.

**Requirement**
Sensor that transmits signals to trigger a cleaning cycle, e.g. UV/VIS sensor

<table>
<thead>
<tr>
<th>Settings</th>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pulse length</td>
<td>Automatic</td>
<td></td>
<td>The duration of the air cleaning process is programmed in the sensor. The relay automatically takes over the cleaning duration from the sensor. The relay finishes the cleaning after the selected interval.</td>
</tr>
<tr>
<td></td>
<td>0.5 s</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1 s</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 s</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3 s</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Settings of the cleaning process can be done in the SETTINGS menu of the respective sensor.
6.4.8 Cleaning

Function

The Cleaning function enables the time controlled automatic start of the sensor cleaning function with the aid of a relay of the Universal Transmitter. The relay controls the DIQ/CHV valve module and switches on or off the compressed air for the CH sensor cleaning head.

In order to set up the Cleaning function for a relay output, the relay output must be linked with a sensor (see section 6.2.1).

The assigned relay always works as a closer.

The cleaning cycle consists of Cleaning duration and Adjustment time.

During the cleaning cycle the Clean display flashes. The outputs linked with this sensor are frozen. The maintenance condition is active.

After the Cleaning duration, the relay is opened. During the following Adjustment time the outputs remain blocked.

The outputs linked with this sensor are only released when the cleaning cycle is completed. The Clean display disappears. The maintenance condition is finished.

Testing the operativeness

You can test the operativeness of the cleaning system as follows: manually open or close the relay with the Manual control function (see section 6.4.9) and, while doing so, check the behavior of the cleaning system.

Alternatively, you can test the operativeness of the cleaning system by checking the performance of the function at the start time set up (reference time ± interval). To perform a test immediately, you can set the reference time so that the next cleaning cycle will start in a few minutes (settings: see following table).
## Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reference time (h)</td>
<td>0 ... 23 h</td>
<td>Time at which a cleaning cycle is started. Further cleaning cycles will be performed at the times specified by the cleaning interval.</td>
</tr>
<tr>
<td>Reference time (min)</td>
<td>0 ... 60 min</td>
<td></td>
</tr>
<tr>
<td>Interval unit</td>
<td>1 .. 7 d</td>
<td>Selection of range and unit for the Cleaning interval.</td>
</tr>
<tr>
<td></td>
<td>1 .. 24 h</td>
<td></td>
</tr>
<tr>
<td></td>
<td>5 .. 60 min</td>
<td></td>
</tr>
<tr>
<td>Cleaning interval</td>
<td>1/2/3/4/5/6/7 d</td>
<td>Repeat interval for the cleaning function: Time between the start time of a cleaning cycle and the start time of the next cleaning cycle*.</td>
</tr>
<tr>
<td></td>
<td>or: 1/2/3/4/6/8/12/24 h</td>
<td></td>
</tr>
<tr>
<td></td>
<td>or: 5/10/15/20/30/60 min</td>
<td></td>
</tr>
<tr>
<td>Cleaning duration</td>
<td>0 ... 300 s</td>
<td>Duration of the cleaning</td>
</tr>
<tr>
<td>Adjustment time</td>
<td>0 ... 900 s</td>
<td>Time extension to allow the sensor to adjust to the test sample after cleaning.</td>
</tr>
</tbody>
</table>

* With short cleaning intervals, the adjustable values for the Cleaning duration and Adjustment time are limited. The following values apply:

<table>
<thead>
<tr>
<th>Cleaning interval</th>
<th>Cleaning duration</th>
<th>Adjustment time</th>
</tr>
</thead>
<tbody>
<tr>
<td>≤ 10 min</td>
<td>max. 60 s</td>
<td>max. 120 s</td>
</tr>
<tr>
<td>≤ 20 min</td>
<td>max. 180 s</td>
<td>max. 300 s</td>
</tr>
</tbody>
</table>

With this, the cleaning times are fixed. They only change when the reference time is changed.

The reference time and all further cleaning times relate to the date and time of the system clock. The setting of the system clock can be found in section 5.5.
## Example

<table>
<thead>
<tr>
<th>Setting</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reference time (h): 12</td>
<td>Reference time: 12:00 hours This specifies the following start times:</td>
</tr>
<tr>
<td>Reference time (min): 0</td>
<td>04:00, 12:00 and 20:00 hours</td>
</tr>
<tr>
<td>Interval unit: 8 h</td>
<td></td>
</tr>
<tr>
<td>Cleaning interval: 8 h</td>
<td></td>
</tr>
</tbody>
</table>

### Fig. 6-12 Cleaning cycle

1. **Reference time**
   - Start of a cleaning cycle (t1)
   - Start of the specified Cleaning duration (t1a)

2. **End of the specified Cleaning duration (t1a)**
   - Start of the specified Adjustment time (t1b)

3. **End of the specified Adjustment time (t1b)**
   - End of the cleaning cycle (t1)

4. **Reference time ± Cleaning interval (t2)**
   - Start of a cleaning cycle

- **t1**: Cleaning cycle = Cleaning duration (t1a) Adjustment time (t1b) Linked outputs are frozen.

- **t2**: Cleaning interval
Canceling the cleaning

A running cleaning cycle is canceled:

- **Automatically**
  - If the sensor switches to the inactive condition during the cleaning cycle
- **Manually**
  - By pressing (●)
  - By switching on the maintenance condition

Each time the cleaning cycle is canceled, the relay opens immediately.

If the cleaning cycle is canceled automatically, the outputs linked to the sensor are released immediately.

If the cleaning cycle is canceled manually, the sensor is in the maintenance condition. The linked outputs are only released after the maintenance condition was terminated manually.

The next cleaning cycle will be performed at the time set up.

In case of a power failure, all relays open. The cleaning cycle is canceled. The outputs linked with the sensor change to the non-active condition (see section 6.6.2). As soon as the power is available, the outputs are released again. The next cleaning cycle will be performed at the time set up.

6.4.9 Manual control

Function

With the Manual control function, you can test the operativeness of an instrument that is connected to the relay. To do so, close or open the relay manually and, while doing so, check the behavior of the connected instrument.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Relay function</td>
<td>Manual control</td>
<td>The selected relay action is carried out with Save and quit.</td>
</tr>
<tr>
<td>Action</td>
<td>Open Close</td>
<td>Relay action</td>
</tr>
</tbody>
</table>

The settings for other functions in the Relay function menu, as for example Frequency controller and Pulse-width output, are retained while the Manual control is carried out.
6.5 Setting tables for current outputs

6.5.1 Functions and settings

To set a current output its function has to be selected first. Then the relevant setting table is displayed:

<table>
<thead>
<tr>
<th>Function of current outputs and relevant setting tables</th>
<th>Function</th>
<th>Setting table</th>
</tr>
</thead>
<tbody>
<tr>
<td>No function</td>
<td>The current output is not used.</td>
<td></td>
</tr>
<tr>
<td>Recorder</td>
<td>see section 6.5.2</td>
<td></td>
</tr>
<tr>
<td>PID controller</td>
<td>see section 6.5.3</td>
<td></td>
</tr>
<tr>
<td>Fixed current value</td>
<td>see section 6.5.4</td>
<td></td>
</tr>
</tbody>
</table>

6.5.2 Recorder

Function

The measured values of the linked sensor at the current output are set up as current intensity in the Recorder application. The output of measured values is laid down in the Recorder type, Start value and End value settings.

Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Recorder type</td>
<td>0 to 20 mA or 4 to 20 mA</td>
<td></td>
</tr>
<tr>
<td>Start value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Minimum spacing: [ \leq 5% \text{ of the measuring range (sensor-dependent)} ]</td>
</tr>
<tr>
<td>End value</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Measured variable</td>
<td>Main variable Adjoining variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Attenuation</td>
<td>0 ... 40 mA/s</td>
<td>Speed of change of the output current (mA/s) in the case of an erratic change of the input signal.</td>
</tr>
<tr>
<td>I -&gt; OFL/UFL</td>
<td>Error</td>
<td>Current values outside the range between Start value and End value are considered as errors. The current output reacts as specified under Behavior at error (see below).</td>
</tr>
<tr>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td>Limitation</td>
<td>The current at the output is limited to the Start value or End value.</td>
<td></td>
</tr>
<tr>
<td>Behavior at error</td>
<td>Fixed current value</td>
<td>In case of system errors and sensor errors, and in case of measured values outside the range between Start value and End value, the current output supplies the specified fixed current value. Possible values: 0 ... 21 mA.</td>
</tr>
<tr>
<td></td>
<td>Unchanged</td>
<td>The current at the output remains unchanged.</td>
</tr>
</tbody>
</table>
### 6.5.3 PID controller

**Function**

With the PID controller function, you can use an output as a controller output. The controller can be configured as a Proportional controller with a switchable Integral and Derivative controller part (PID controller).

The control mode of the PID controller is described by the following equation:

\[
I_{Controller} = I_0 + K \left( x_e + \frac{I}{T_i} \int x_e dt + T_d \frac{dx_e}{dt} \right)
\]

with:

\[
K = \frac{I_{max} - I_{min}}{X_p}
\]

\[
x_e = x_{nom} - x_{actual}
\]

\[
I_{min} \leq I_{Controller} \leq I_{max}
\]

- \(I_{Controller}\): Current at the controller output at time \(t\)
- \(I_0\): Current at output if \(x_{actual} = x_{nominal}\)
- \(K\): Gain
- \(X_p\): Proportional band
- \(x_e\): Error signal
- \(x_{actual}\): Actual value (current measured value)
- \(x_{nom}\): Nominal value
- \(t_i\): Integral control part
- \(t_d\): Derivative control part
- \(t\): Time
- \(I_{min}\): Lower current limitation
- \(I_{max}\): Upper current limitation

The adjustable control parameters are \(x_{nominal}, I_0, X_p, I_{min}, I_{max}, t_i\) and \(T_d\) (see setting table on page 6-30).
By activating or deactivating the Integral (ti) and Derivative (td) controller part, the following controller types can be configured:

<table>
<thead>
<tr>
<th>Controller type</th>
<th>td [s]</th>
<th>ti [s]</th>
</tr>
</thead>
<tbody>
<tr>
<td>P controller</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>PI controller</td>
<td>0</td>
<td>1 to 9999</td>
</tr>
<tr>
<td>PD controller</td>
<td>1 to 9999</td>
<td>0</td>
</tr>
<tr>
<td>PID controller</td>
<td>1 to 9999</td>
<td>1 to 9999</td>
</tr>
</tbody>
</table>

Characteristic curve of the proportional controller

For a P controller, the interrelationship between the measured value and current I at the controller output forms the following characteristic curve:

![Proportional controller characteristic curve](image)

Fig. 6-13  Proportional controller (negative characteristic curve)

The proportional band Xp is limited by the measuring range of the linked sensor. If a value is entered for the parameter Xp that is greater than zero, the controller has a negative characteristic curve (example Fig. 6-13). To obtain a positive characteristic curve, a negative value must be entered for Xp.
Application example

● Feedback control of the D. O. concentration
● Sensor: TriOxmatic 700 IQ (measuring range: 0 ... 60 mg/l)

<table>
<thead>
<tr>
<th>Control parameters</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nominal value</td>
<td>4 mg/l</td>
</tr>
<tr>
<td>Xp</td>
<td>10 % of the measuring range or 6 mg/l</td>
</tr>
<tr>
<td>Imin</td>
<td>8 mA</td>
</tr>
<tr>
<td>Imax</td>
<td>14 mA</td>
</tr>
<tr>
<td>Io</td>
<td>12 mA</td>
</tr>
<tr>
<td>ti</td>
<td>0 s (no I controller part)</td>
</tr>
<tr>
<td>td</td>
<td>0 s (no D controller part)</td>
</tr>
</tbody>
</table>

The control parameters form the following (negative) characteristic curve:

The controller works with the following gain:

\[ K = \frac{6 \text{ mA}}{6 \text{ mg/l}} = 1 \text{ mA/mg/l} \]
Within the proportional band, a concentration increase by 1 mg/l causes a decrease of the current output by 1 mA. If, for example, the measured concentration is 5 mg/l, 11 mA are output:

\[
I_{\text{Controller}} = 12 \text{ mA} + 1 \text{ mA} \cdot \left(\frac{\text{mg/l}}{\text{mg/l}} \cdot (4 \text{ mg/l} - 5 \text{ mg/l})\right)
\]

\[
I_{\text{Controller}} = 12 \text{ mA} + 1 \text{ mA} \cdot (-1 \text{ mg/l}) = 11 \text{ mA}
\]

The highest concentration with which the controller works within the proportional band is 8 mg/l (corresponding to \( I_{\text{min}} = 8 \text{ mA} \)), the lowest one is 2 mg/l (corresponding to \( I_{\text{max}} = 14 \text{ mA} \)).

### Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.).</td>
</tr>
<tr>
<td></td>
<td>Adjoining variable</td>
<td>Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Nominal value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Nominal value the measured value is regulated to</td>
</tr>
<tr>
<td>( X_p )</td>
<td>5 ... 100 %</td>
<td>Proportional band of the controller. Negative values result in a positive characteristic curve.</td>
</tr>
<tr>
<td></td>
<td>-5 ... -100 %</td>
<td>of the measuring range</td>
</tr>
<tr>
<td>( I_{\text{min}} )</td>
<td>0 ... 20 mA</td>
<td>Lower current limitation *</td>
</tr>
<tr>
<td>( I_{\text{max}} )</td>
<td>0 ... 20 mA</td>
<td>Upper current limitation *</td>
</tr>
<tr>
<td></td>
<td></td>
<td>* Note: Spacing between ( I_{\text{min}} ) and ( I_{\text{max}} ): at least 5 mA</td>
</tr>
<tr>
<td>Setting</td>
<td>Selection/Values</td>
<td>Explanation</td>
</tr>
<tr>
<td>-----------</td>
<td>------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Io</td>
<td>0 ... 20 mA</td>
<td>Current value on the output if the measured value equals the Nominal value</td>
</tr>
<tr>
<td>ti</td>
<td>0 ... 9999 s</td>
<td>Hold-back time: Integral part of the controller (0 = not effective)</td>
</tr>
<tr>
<td>td</td>
<td>0 ... 9999 s</td>
<td>Reset time: Derivative part of the controller (0 = not effective)</td>
</tr>
<tr>
<td>Behavior at error</td>
<td>Fixed current value</td>
<td>In the case of an error, the current output supplies the current value defined in the Current with error field (any in the range 0 ... 21 mA).</td>
</tr>
<tr>
<td></td>
<td>Unchanged</td>
<td>In the case of an error, the current on the output remains unchanged.</td>
</tr>
</tbody>
</table>
6.5.4  **Fixed current value**

**Function**

With the Fixed current value function, you can test the operativeness of the instruments connected to the outputs: output different current values to the output and, while doing so, check the behavior of the connected instrument.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current output</td>
<td>Fixed current value</td>
<td>Using Save and quit, the nominal amperage that was input as Inom is output.</td>
</tr>
<tr>
<td>Inom</td>
<td>0 ... 20 mA</td>
<td>The nominal amperage that is output.</td>
</tr>
</tbody>
</table>

The settings for other functions in the Current output menu, as for example PID controller and Recorder, are retained while the Fixed current value is carried out.
6.6 Behavior of linked outputs

6.6.1 Behavior in case of error

For linked relay outputs or current outputs, you can determine the behavior of the outputs in case of errors. Depending on the use of the output, the behavior in case of errors is set in the following menus:

<table>
<thead>
<tr>
<th>Output</th>
<th>menu</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limit indicator</td>
<td>Behavior at error (see section 6.4.4)</td>
</tr>
<tr>
<td>Frequency controller</td>
<td>Frequency with error (see section 6.4.5)</td>
</tr>
<tr>
<td>Pulse-width output</td>
<td>Error pulse width (see section 6.4.6)</td>
</tr>
<tr>
<td>Recorder</td>
<td>Current with error (see section 6.5.2)</td>
</tr>
</tbody>
</table>

The specified behavior occurs with the following errors.

- The system is in the maintenance condition or displays Init, ----, Cal, Clean, Error or OFL.
  The meaning of these displays is given in section 4.2 of this operating manual.
- The supply voltage is too low.

6.6.2 Behavior in non-operative condition

An output is non-operative when no function is activated for the output. An output becomes non-operative in case of

- Power failure
  (As soon as the supply voltage is sufficient again, the non-operative condition of the outputs ends. The outputs function as specified by the user again.)
- Erasing a link to a sensor
- Changing the Measuring mode sensor setting for a linked sensor
- Changing the Measuring range sensor setting for a linked sensor

Before editing sensor settings a note appears on the display to inform you that links will be erased when you change the Measuring mode or Measuring range sensor setting.

## Settings in the non-active condition

<table>
<thead>
<tr>
<th>Current output</th>
<th>Relay output</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current: 0 A</td>
<td>Relay: Open</td>
</tr>
</tbody>
</table>

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7 Maintenance and cleaning

7.1 Maintenance

Maintenance activities

<table>
<thead>
<tr>
<th>Component</th>
<th>Maintenance</th>
</tr>
</thead>
<tbody>
<tr>
<td>IQ sensors</td>
<td>Depending on the type of sensor (see the component operating manual of the sensor)</td>
</tr>
<tr>
<td>DIQ/S 182, DIQ modules, MIQ modules</td>
<td>No maintenance required</td>
</tr>
</tbody>
</table>

7.2 Cleaning

Clean components mounted in the open of gross contamination as necessary. We recommend to clean the worst of the dirt on the enclosure and the area around it each time before opening in order to prevent gross contamination from entering the open enclosure.

To clean the module, wipe the enclosure surfaces with a damp, lint-free cloth. If compressed air is available on site, blow off the worst of the dirt beforehand. Keep the enclosure closed while doing so.

NOTE

*Do not use high-pressure water blasters for cleaning (danger of water penetration!). Also do not use aggressive cleaning agents such as alcohol, organic solvents or chemical detergents. These types of cleaning agent can attack the surface of the housing.*

IQ sensors

The cleaning of the IQ sensors depends greatly on the respective application. Instructions for this are given in the respective component operating manual.
# 8 What to do if ...

## 8.1 Information on errors

The DIQ/S 182 system performs a comprehensive cyclical self test during operation. While doing so, the system identifies all states that deviate from normal operation and enters corresponding messages in the log book (information or error message).

With the aid of the log book, you can call up instructions on how to clear the error directly on the terminal. The log book is described in detail in section 4.4.3 Sensor status Sxx.

Information on possible errors in IQ sensors and MIQ output modules is given in the chapter WHAT TO DO IF ... of the respective component operating manual.

## 8.2 Error causes and remedies

### The system does no longer react on entries

<table>
<thead>
<tr>
<th>Cause</th>
<th>Remedy</th>
</tr>
</thead>
<tbody>
<tr>
<td>System error</td>
<td>Reset the system: Switch off the power supply and switch it on again after 10 s</td>
</tr>
</tbody>
</table>

### "Error" in the measured value display

<table>
<thead>
<tr>
<th>Cause</th>
<th>Remedy</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication with the IQ Sensor interrupted</td>
<td>Check the cable connection</td>
</tr>
<tr>
<td>Error in the IQ sensor</td>
<td>Disconnect the IQ sensor and reconnect it after 10 s</td>
</tr>
</tbody>
</table>

### The selected system language was not activated for a sensor

<table>
<thead>
<tr>
<th>Cause</th>
<th>Remedy</th>
</tr>
</thead>
<tbody>
<tr>
<td>A system language was selected that is not available in the sensor. The English language was activated instead of the selected system language.</td>
<td>Contact YSI, a software update is required for the respective components</td>
</tr>
</tbody>
</table>
8.3 Replacing system components

8.3.1 Replacing passive components

Passive components include all components that the controller cannot recognize. These include:

- MIQ power supply modules
- DIQ/JB
- DIQ/CHV
- Cables (SNCIQ, SACIQ).

**WARNING**

If the DIQ/S 182 Universal Transmitter is opened and the MIQ/PS power supply module is operating, there is a danger to life due to possible hazard of electric shock from line voltage. Before opening the Universal Transmitter, switch off the system and, if necessary, all external relay circuits that present a hazard of electric shock and secure the system against being switched on again.

Only ever replace components when the system is switched off. Defective components are removed in the reverse order to the installation (see chapter 3 INSTALLATION).

8.3.2 Adding and replacing IQ sensors

Inactive datasets of IQ sensors

If an IQ sensor is removed from the system, its settings remains stored in the Universal Transmitter as an inactive dataset. A dataset contains the following information:

- Serial number of the IQ sensor (and, with it, the type of sensor)
- Display position
- All sensor settings
- All characteristics of the link with an output.

If no suitable inactive dataset is available, a newly connected IQ sensor is recognized and added automatically.

The DIQ/S 182 Universal Transmitter can display and administrate up to two main measured parameters. If necessary, an inactive dataset has to be erased to be able to add a new sensor.

To erase inactive datasets, see page 5-3.
The current calibration data of the IQ sensor is always stored in the sensor. If an IQ sensor is connected that is ready for operation and calibrated, this can be used immediately without the need for recalibration.

If an IQ sensor is connected to the system when an inactive dataset is present, the following cases are possible:

**Case 1:**

The connected IQ sensor is automatically assigned to the inactive dataset and starts to operate again.

**Example:** Maintenance or repair.

This mechanism ensures that all IQ sensors retain their settings and links if an IQ sensor was removed for maintenance, or if the system was temporarily switched off.

**Case 2:**

Operator intervention is required here. The connected IQ sensor can:

- be assigned to the inactive dataset (or one of the inactive datasets).
  **Example:** Replacing an IQ sensor. Make sure that the substitute sensor has at least the software status of the inactive IQ sensor.

- be included as a new module in the list of the sensors.

The operating sequence to do this is described below.
It is always possible to replace components and assign a substitute if the software state of the substitute component is as high or higher as the software version of the original component. Otherwise the component may not be recognized by the Universal Transmitter.

### Operating sequence in case 2

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Connect the IQ sensor.</td>
</tr>
<tr>
<td>2</td>
<td>Change to the measured value display with ( m ). The module database is updated. The following display appears (example):</td>
</tr>
</tbody>
</table>

### NEW SENSOR

- 700IQ
- 99160022
- Substitute sensor
- Add as new sensor

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>Select the required option with ( w ) and confirm with ( g ).</td>
</tr>
</tbody>
</table>
- If Add new sensor was selected, the system changes directly to the measured value display. As soon as the IQ sensor is ready for operation, it delivers a measured value.
- If Assign sensor as a substitute was selected, a list with the assignable sensors or inactive datasets appears.

### ASSIGNABLE SENSORS

- 801 99160001

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
</table>
| 4 | Select the required sensor with \( w \) and confirm with \( g \). The system changes to the measured value display. The IQ sensor takes over all settings of the inactive dataset. As soon as the IQ sensor is ready for operation, it delivers a measured value.
9 Technical data

9.1 DIQ/S 182

Dimensions

Front view:

![Diagram of the front view of the DIQ/S 182]

Side view:

![Diagram of the side view of the DIQ/S 182]

Rear view:

![Diagram of the rear view of the DIQ/S 182]

Stack mounting:

![Diagram of the stack mounting of the DIQ/S 182]

Fig. 9-1 Dimension drawing of the DIQ/S 182 (dimensions in mm)

Test marks  cETLus, CE
## Mechanical construction

<table>
<thead>
<tr>
<th>Enclosure material</th>
<th>Polycarbonate with 20 % glass fiber</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weight</td>
<td>Approx. 0.7 kg</td>
</tr>
<tr>
<td>Type of protection</td>
<td>- IP 66</td>
</tr>
<tr>
<td></td>
<td>- corresponds to NEMA 4X</td>
</tr>
<tr>
<td></td>
<td>The DIQ/S 182 Universal Transmitter is</td>
</tr>
<tr>
<td></td>
<td>not suitable for Conduit Connection</td>
</tr>
</tbody>
</table>

## Ambient conditions

### Temperature

<table>
<thead>
<tr>
<th>Operation</th>
<th>-20 °C ... 55 °C (-4 ... 131 °F)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Storage</td>
<td>-25 °C ... 65 °C (-13 ... 149 °F)</td>
</tr>
</tbody>
</table>

### Relative humidity

<table>
<thead>
<tr>
<th>Yearly average</th>
<th>≤ 90 %</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dew formation</td>
<td>Possible</td>
</tr>
</tbody>
</table>

| Site altitude       | Max. 2000 m above sea level                     |

## Electrical data

**DIQ/S 182 (line power version)**

<table>
<thead>
<tr>
<th>Power supply</th>
<th>Nominal voltage: 100 ... 240 VAC ± 10 %</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Frequency: 50/60 Hz</td>
</tr>
<tr>
<td></td>
<td>according to DIN IEC 60038</td>
</tr>
<tr>
<td></td>
<td>Line power connection: 2 pin, N and L</td>
</tr>
<tr>
<td>Line cross-section of mains connection:</td>
<td>Europe: 1.5 ... 4.0 mm²</td>
</tr>
<tr>
<td></td>
<td>USA: AWG 14 ... 12</td>
</tr>
<tr>
<td>Fuse rating on the operator side:</td>
<td>max. 16 A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Protective class</th>
<th>II</th>
</tr>
</thead>
<tbody>
<tr>
<td>Overvoltage category</td>
<td>II</td>
</tr>
<tr>
<td>Power consumption</td>
<td>max. approx. 12 W</td>
</tr>
</tbody>
</table>
Electrical data
DIQ/S 182/24V
(24 V AD/DC version)

Supply
Nominal voltage: 24 V AC/DC ± 10 %
protective low voltage
SELV (Safety Extra Low Voltage)

AC frequency: 50/60 Hz according to DIN IEC 60038

Connection: 2 pin

Line cross-section of connections:
Europe: 1.5 ... 4.0 mm²
USA: AWG 14 ... 12

Fuse rating on the operator side: max. 16 A

Power consumption: max. approx. 12 W

Electrical connections
DIQ/S 182
(line power version)

Terminal strip inside the enclosure:

Electrical connections
DIQ/S 182/24V
(24 V AC/DC version)

Terminal strip inside the enclosure:
### Relay (3 x)

<table>
<thead>
<tr>
<th>Output</th>
<th>Galvanically separated</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. switching voltage</td>
<td>240 VAC or 24 VDC</td>
</tr>
<tr>
<td>Max. switching current</td>
<td>2 A (AC and DC)</td>
</tr>
<tr>
<td>Installation requirements</td>
<td>Fuse rating on the operator side: max. 2 A</td>
</tr>
<tr>
<td>Relay functions</td>
<td>Programmable as:</td>
</tr>
<tr>
<td></td>
<td>- Opener or closer</td>
</tr>
<tr>
<td></td>
<td>- Limit monitor</td>
</tr>
<tr>
<td></td>
<td>- Monitoring of the warning and error signals of the DIQ/S 182</td>
</tr>
<tr>
<td></td>
<td>- Proportional frequency output</td>
</tr>
<tr>
<td></td>
<td>- Proportional pulse width output</td>
</tr>
</tbody>
</table>

### Current outputs (2 x)

<table>
<thead>
<tr>
<th>Output</th>
<th>Galvanically separated from the sensors</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output current</td>
<td>Can be switched between 0 - 20 mA and 4 - 20 mA</td>
</tr>
<tr>
<td></td>
<td>In the case of errors, can be set to: 0 ... 21 mA</td>
</tr>
<tr>
<td>Max. initial output voltage</td>
<td>24 V, in the case of missing or incorrect burden</td>
</tr>
<tr>
<td>Accuracy</td>
<td>0.3 % of current value ± 50 µA, load max. 500 Ω</td>
</tr>
<tr>
<td>Functions</td>
<td>Programmable:</td>
</tr>
<tr>
<td></td>
<td>- Recorder attenuation, adjustable 0 - 40 mA/s</td>
</tr>
<tr>
<td></td>
<td>- Error behavior can be set as required 0 ... 21 mA</td>
</tr>
<tr>
<td></td>
<td>- Error behavior according to Namur NE43 can be selected</td>
</tr>
<tr>
<td></td>
<td>- Positive and negative characteristic curve</td>
</tr>
<tr>
<td></td>
<td>- PID controller</td>
</tr>
</tbody>
</table>
### Terminals

**Terminal type**
- Screw-type terminal strip, accessible by opening the lid

**Terminal ranges**
- Solid wires: 0.2 ... 4.0 mm²
- AWG 24 ... 12
- Flexible wires: 0.2 ... 2.5 mm²

### Cable glands

**Suitable for cable diameter**
- 4.5 ... 10 mm or 7 ... 13 mm

### EMC product and system characteristics

**EN 61326**
- EMC requirements for electrical resources for control technology and laboratory use
  - Resources for industrial areas, intended for indispensable operation
  - Interference emission limits for resources of class B

**System lightning protection**
- Extended protective characteristics as opposed to EN 61326

**FCC, class A**

---

Any combination of the DIQ/S 182 with IQ SENSOR NET products in a user-specific system achieves the listed EMC characteristics.

### Instrument safety

**Applicable norms**
- EN 61010-1
- UL 61010-1
- CAN/CSA C22.2#61010-1
9.2 MIQ modules

Technical data on special MIQ modules are given in the respective operating manuals.

**Dimensions**

Fig. 9-2 Dimension drawing of MIQ module (dimensions in mm)
<table>
<thead>
<tr>
<th><strong>Mechanical construction</strong></th>
<th>Maximum number of MIQ modules in a module stack</th>
<th>2 plus Universal Transmitter DIQ/S 182</th>
</tr>
</thead>
<tbody>
<tr>
<td>Enclosure material</td>
<td>Polycarbonate with 20 % glass fiber</td>
<td></td>
</tr>
<tr>
<td>Weight</td>
<td>Approx. 0.5 kg (type-dependent)</td>
<td></td>
</tr>
<tr>
<td>Type of protection</td>
<td>- IP 66</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- In accordance with NEMA 4X MIQ modules are not suitable for conduit connection</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>Terminal connections</strong></th>
<th>SENSORNET connections</th>
<th>At least two in each MIQ module.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Further connections</td>
<td>Module-dependent</td>
<td></td>
</tr>
<tr>
<td>Terminal type</td>
<td>Screw-type terminal strip, accessible by opening the lid</td>
<td></td>
</tr>
<tr>
<td>Terminal ranges</td>
<td>Solid wires: 0.2 ... 4.0 mm²</td>
<td>AWG 24 ... 12</td>
</tr>
<tr>
<td></td>
<td>Flexible wires: 0.2 ... 2.5 mm²</td>
<td></td>
</tr>
</tbody>
</table>

| **Cable glands**                            | Suitable for cable diameter                     | 4.5 ... 10 mm or 7 ... 13 mm          |
9.3 DIQ/J B

Dimensions

Fig. 9-3 Dimension drawing of DIQ/J B (dimensions in mm)

Mechanical construction

<table>
<thead>
<tr>
<th>Enclosure material</th>
<th>Polystyrene</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weight</td>
<td>Approx. 0.2 kg</td>
</tr>
<tr>
<td>Type of protection</td>
<td>IP 66</td>
</tr>
</tbody>
</table>

Electrical connections

(7 passive, potential free terminals for line extension or branching)

Terminals

<table>
<thead>
<tr>
<th>Terminal type</th>
<th>Screw-type terminal strip</th>
</tr>
</thead>
</table>
| Terminal ranges | Solid wires: 0.2 ... 4.0 mm²  
                  | AWG 24 ... 12 |
|                | Flexible wires: 0.2 ... 2.5 mm² |
| Cable feeds   | Prepared openings for installing two screwed cable glands M16 x 1.5 both on the upper and underside |
9.4 DIQ/CHV

**Dimensions**

![Diagram of DIQ/CHV dimensions](image)

Fig. 9-4 Dimension drawing of DIQ/CHV (dimensions in mm)

**Mechanical construction**

<table>
<thead>
<tr>
<th>Property</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Enclosure material</td>
<td>Polystyrene</td>
</tr>
<tr>
<td>Weight</td>
<td>Approx. 0.3 kg</td>
</tr>
<tr>
<td>Type of protection</td>
<td>IP 66</td>
</tr>
</tbody>
</table>

**Electrical connections**

- 1 x valve switching contact
- 4 x potential-free terminals to connect interface lines

Terminal strip inside the enclosure:

![Terminal strip diagram](image)

**Terminals**

<table>
<thead>
<tr>
<th>Property</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Terminal type</td>
<td>Screw-type terminal strip</td>
</tr>
</tbody>
</table>
| Terminal ranges  | Solid wires: 0.2 ... 4.0 mm²  
                  | AWG 24 ... 12  
                  | Flexible wires: 0.2 ... 2.5 mm² |
| Cable feeds      | Prepared openings for installing two screwed cable glands M16 x 1.5 on the upper side |
### Technical data

#### System 182

<table>
<thead>
<tr>
<th>Valve circuits</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Switching voltage</td>
<td>Approx. 22 V</td>
</tr>
<tr>
<td>Max. switching current</td>
<td>Approx. 40 mA</td>
</tr>
</tbody>
</table>

**NOTE**

*The valve may only be operated with the auxiliary voltage of the DIQ/S 182 Universal Transmitter.*

<table>
<thead>
<tr>
<th>Compressed air</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Required air quality</td>
<td>Dry, free of dust and oil</td>
</tr>
<tr>
<td>Operating pressure</td>
<td>Max. $7 \times 10^5$ Pa (7 bar) absolute</td>
</tr>
<tr>
<td>Connections on the DIQ/CHV</td>
<td>6 mm hose nozzles</td>
</tr>
</tbody>
</table>
9.5 Space required by mounted components

Wall mounting and top hat rail mounting

Fig. 9-5  Space required for wall and top hat rail mounting: (dimensions in mm)

Panel mounting

Fig. 9-6  Space required for panel mounting (dimensions in mm)
## 10 Accessories and options

<table>
<thead>
<tr>
<th>Description</th>
<th>Model</th>
<th>Order no.</th>
</tr>
</thead>
<tbody>
<tr>
<td>IQ SENSOR NET cable - please specify the required length in m with your order</td>
<td>SNCIQ</td>
<td>480 046Y</td>
</tr>
<tr>
<td></td>
<td>SNCIQ/UG</td>
<td>480 047Y</td>
</tr>
<tr>
<td>IQ sensor connection cable</td>
<td></td>
<td></td>
</tr>
<tr>
<td>- 1.5 m</td>
<td>SACIQ-1.5</td>
<td>480 040Y</td>
</tr>
<tr>
<td>- 7.0 m</td>
<td>SACIQ-7.0</td>
<td>480 042Y</td>
</tr>
<tr>
<td>- 15.0 m</td>
<td>SACIQ-15.0</td>
<td>480 044Y</td>
</tr>
<tr>
<td>- Special length up to max. 100 m</td>
<td>SACIQ-SO</td>
<td>480 041YY</td>
</tr>
<tr>
<td>- 20 m (seawater version)</td>
<td>SACIQ-20.0 SW</td>
<td>480 045Y</td>
</tr>
<tr>
<td>- 25 m (seawater version)</td>
<td>SACIQ-25.0 SW</td>
<td>480 066Y</td>
</tr>
<tr>
<td>- 50 m (seawater version)</td>
<td>SACIQ-50.0 SW</td>
<td>480 060Y</td>
</tr>
<tr>
<td>- 75 m (seawater version)</td>
<td>SACIQ-75.0 SW</td>
<td>480 067Y</td>
</tr>
<tr>
<td>- 100 m (seawater version)</td>
<td>SACIQ-SO SW</td>
<td>480 062Y</td>
</tr>
<tr>
<td>- Special length (seawater version)</td>
<td>SACIQ-SO SW</td>
<td>480 064VY</td>
</tr>
<tr>
<td>Set with four cable glands for cable sheath</td>
<td>EW/1</td>
<td>480 051Y</td>
</tr>
<tr>
<td>diameter of 7 to 13 mm</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Branching module</td>
<td>DIQ/J B</td>
<td>472 005Y</td>
</tr>
<tr>
<td>Valve module</td>
<td>DIQ/CHV</td>
<td>472 007Y</td>
</tr>
<tr>
<td>Set for mounting of one or two DIQ modules to a YSI mounting stand</td>
<td>MS/DIQ</td>
<td>472 009Y</td>
</tr>
<tr>
<td>Sun shield for the DIQ/S 182</td>
<td>SSH/IQ</td>
<td>109 295Y</td>
</tr>
<tr>
<td>Set for wall mounting of the DIQ/S 182 or an MIQ module</td>
<td>WMS/IQ</td>
<td>480 052Y</td>
</tr>
<tr>
<td>Set for panel mounting of the DIQ/S 182 or an MIQ module; switch panel aperture 138 x 138 mm according to DIN 43700 or IEC 473 (max. thickness 15 mm)</td>
<td>PMS/IQ</td>
<td>480 048Y</td>
</tr>
<tr>
<td>Set for mounting of the DIQ/S 182 or an MIQ module on a 35 mm top hat rail according to EN 50022</td>
<td>THS/IQ</td>
<td>480 050Y</td>
</tr>
</tbody>
</table>

Other accessories for the System 182 are given in the YSI catalog or on the Internet.
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12.1 Forgotten the password?

Proceeding: prompting the password

1 Open the SETTINGS menu with $S$.

2 Depending on the password to be prompted, use $\uparrow$ and $\downarrow$ to select and confirm the menu item, Settings $\leftarrow$ / $\rightarrow$ or Calibrate $\leftarrow$ / $\rightarrow$. The following display appears:

```
SETTINGS $\leftarrow$
Activate password
Change password
```

or

```
SETTINGS $\rightarrow$
Deactivate password
```

3 First press $\rightarrow$, then press $S$. The current password is displayed.

```
PASSWORD
Current password is:
3042
```

4 Quit the display of the password with $\rightarrow$.

12.2 Default passwords

In the default condition of the Universal Transmitter both passwords are set to 1000.
13 Contact Information

13.1 Ordering & Technical Support

Telephone: (800) 897-4151
(937) 767-7241
Monday through Friday, 8:00 AM to 5:00 PM ET

Fax: (937) 767-1058

Email: environmental@ysi.com

Mail: YSI Incorporated
1725 Brannum Lane
Yellow Springs, OH 45387
USA

Internet: www.ysi.com

When placing an order please have the following information available:

- YSI account number (if available)
- Name and Phone Number
- Model number or brief description
- Billing and shipping address
- Quantity
- Purchase Order or Credit Card

13.2 Service Information

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When returning a product for service, include the Product Return form with cleaning certification. The form must be completely filled out for an YSI Service Center to accept the instrument for service. The Product Return form may be downloaded at www.ysi.com and clicking on the 'Support' tab.
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IQ SENSORNet
MIQ/CR3; DIQ/CR3

IQ SENSORNet COMBI OUTPUT MODULE
For the most recent version of the manual, please visit www.ysi.com.
MIQ/CR3; DIQ/CR3 - List of contents

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1 Overview

1.1 How to use this component operating manual

The IQ SENSORNET operating manual has a modular structure like the IQ SENSORNET itself. It consists of a system operating manual and the operating manuals of all the components used.

Please file this component operating manual into the ring binder of the system operating manual.
1.2 Features of the combi output module

General characteristics
The combi output module has three current outputs and three relay outputs. You can link current outputs and relay outputs to sensors. The linked current outputs and relay outputs can, for example, be used to monitor sensors or to output measurement data. Unlinked relay outputs can be used for general monitoring functions.

With the standard MIQ module housing, the combi output module has the same characteristics as all MIQ modules regarding stability, leakproofness and weather resistance. It also provides the same wide variety of installation options (stacked mounting, canopy mounting, tophat rail mounting, etc.).

Instrument types
The MIQ/CR3 and DIQ/CR3 combi output modules differ in their compatibility with the individual IQ SENSORNET system families.

<table>
<thead>
<tr>
<th>System</th>
<th>Compatible combi output module</th>
</tr>
</thead>
<tbody>
<tr>
<td>2020 XT</td>
<td>MIQ/CR3</td>
</tr>
<tr>
<td>182</td>
<td>DIQ/CR3</td>
</tr>
</tbody>
</table>

Terminal strip
The combi output module has the following electrical connections on the terminal strip inside the housing:
- 3 x relay contact
- 3 x current output
- 2 x SENSORNET connection
2 Safety instructions

This operating manual contains special instructions that must be followed during the installation of the combi output module. Thus, it is essential for the operator to read this component operating manual before carrying out any work with the system. In addition to this manual, the SAFETY chapter of the IQ SENSORNET system operating manual must be followed.

Always keep this component operating manual together with the system operating manual and all other component operating manuals in the vicinity of the IQ SENSORNET system.

Special user qualifications
External circuits carrying mains voltage must only be connected to the relay contacts by a qualified electrician.

General safety instructions
Safety instructions in this operating manual are indicated by the warning symbol (triangle) in the left column. The signal word (e.g. "Caution") indicates the danger level:

Warning indicates instructions that must be followed precisely in order to prevent serious dangers to personnel.

Caution indicates instructions that must be followed precisely in order to avoid slight injuries to personnel or damage to the instrument or the environment.

Other labels
Note
This symbol indicates instructions that describe special features.

Note
indicates cross-references to other documents, e.g. operating manuals.
2.1 Authorized use

The authorized use of the combi output module consists of providing relay and current outputs in the IQ SENSORNET. Please observe the technical specifications according to chapter 6 TECHNICAL DATA. Only operation according to the instructions in this operating manual is authorized.

Any other use is considered to be unauthorized. Unauthorized use invalidates any claims with regard to the guarantee.

2.2 General safety instructions

The combi output module is constructed and inspected according to the relevant guidelines and norms for electronic instruments (see chapter 6 TECHNICAL DATA). It left the factory in a safe and secure technical condition.

**Function and operational safety**

The failure-free function and operational safety of the combi output module is only guaranteed if the generally applicable safety measures and the special safety instructions in this operating manual are followed during its use.

The failure-free function and operational safety of the combi output module is only guaranteed under the environmental conditions that are specified in chapter 6 TECHNICAL DATA.

**Safe operation**

If safe operation is no longer possible, the combi output module must be taken out of operation and secured against inadvertent operation. Safe operation is no longer possible if the combi output module:

- has been damaged in transport
- has been stored under adverse conditions for a lengthy period of time
- is visibly damaged
- no longer operates as described in this manual.

If you are in any doubt, contact the supplier of your combi output module.
3 Installation

3.1 Scope of delivery

The scope of delivery of the combi output module is listed in the INSTALLATION chapter of the system operating manual.

3.2 Safety requirements on the electrical installation

Electrical equipment (e.g. motors, contactors, cables, lines, relays) must meet the following requirements:

- Conformity with national regulations (e.g. NEC, VDE and IEC)
- Suitability for the electrical conditions at the installation site
  - Maximum operating voltage
  - Maximum operating current
- Suitability for the environmental conditions at the installation site
  - Temperature resistance (minimum and maximum temperature)
  - Stability against UV light when used outdoors
  - Protection against water and dust (Nema or IP protection class).
- Suitable fusing of the electrical circuit
  - Overcurrent fuses (in accordance with the technical data of the device input or output)
  - Overvoltage class II surge limiters
- Suitable disconnecting device (e.g. switch or circuit breaker) for the mains supply of permanently mounted equipment with separate mains connection
  - in compliance with the following regulations
    - IEC 60947-1
    - IEC 60947-3
  - in the vicinity of the equipment (recommendation)
- Flame-resistant (cables and lines), in compliance with the following regulations
  - UL 2556 VW-1 (for USA, Canada)
  - IEC 60332-1-2 (outside of USA, Canada)

3.3 Installation in the IQ SENSORnet

The IQ SENSORnet provides a number of options for integrating the combi output module mechanically and electrically in the system (stacked mounting, distributed mounting, etc.). The various types of
installation are described in detail in the INSTALLATION chapter of the system operating manual.

### 3.3.1 Software requirements of the MIQ/CR3 and IQ SENSORNET

Software requirements for the use of the Cleaning function:
- MIQ/CR3: from version 2.20 up
- Controller: from version 2.20 up

If you use a terminal with a software version from 2.20 up, the Clean display flashes. If you use an MIQ/T2020 terminal with a software version lower than 2.20, the Clean display does not appear. The measured value display of the sensor flashes.

Software requirements for use of the functions, PID controller, Manual control and Fixed current value:
- MIQ/CR3: from version 2.30 up

**Note**

It is possible to update the software if your components have older software versions. Please contact YSI.
3.4 Electrical connections: General instructions

Cable glands

All electric cables are fed from below via prepared openings in the enclosure of the module. Cable glands with different clamping ranges are included with the module to provide sealing between the cable and enclosure as well as for strain relief. Select the matching cable gland for the respective cable diameter:

- **Small**, clamping range 4.5 to 10 mm. This cable gland is suitable for all IQ SENSOR NET sensor cables.

- **Large**, clamping range 7 to 13 mm. This cable gland is required for cable sheaths with an outside diameter of more than 10 mm and is screwed into the enclosure via an extension piece.

**Note**

If necessary, you can order more large cable glands in a set of 4 pieces (Model EW/1, Order No. 480 051).
General installation instructions

Observe the following points when attaching connecting wires to the terminal strip:

- Shorten all wires to be used to the length required for the installation.
- Always fit all the ends of the wires with wire end sleeves before connecting them to the terminal strip.
- Any wires that are not used and project into the enclosure must be cut off as closely as possible to the cable gland.
- Screw a small cable gland with sealing ring into each remaining free opening and close it with a blind plug.

Warning

No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that areas safe to contact could come into contact with dangerous voltages which could result in life threatening electric shock when working with the IQ SENSORNET. Always cut off any wires that are not in use as closely as possible to the cable gland.

3.5 Connections to the relay and current outputs

Warning

If external electrical circuits that are subject to the danger of physical contact are incorrectly connected to the relay contacts, there may be a danger of life threatening electric shock. Electrical circuits are regarded to be subject to the danger of physical contact when there are voltages higher than the Safety Extra Low Voltage (SELV).

Pay attention to the following points during installation:

- Electrical circuits subject to the danger of physical contact must only be connected by a qualified electrician.
- Electrical circuits subject to the danger of physical contact must only be connected when they are voltage-free.
- If electrical circuits subject to the danger of physical contact are switched with a relay, no circuit that is not subject to this danger (e.g. the MIQ/CHV module) may be operated in the same output module. Use an additional output module for such applications.
- Switching voltages and switching currents on the relay contacts must not exceed the values specified in chapter 6 TECHNICAL DATA. Protect electrical circuits against currents that are too high with an electrical fuse.
- Only single-phase consumers can be switched with the relays.

Under no circumstances must multiphase consumers be
switched with the aid of several relays (example three-phase current driven pumps). Always switch multiphase consumers via a protective relay.

- After the output module has been installed, it may only be opened if all external voltages have been switched off beforehand.

**Materials required**

- Wire end sleeves, suitable for the connecting wires, with suitable crimping tool
- 4 x screwed cable gland with sealing ring (scope of delivery of the combi output module).

**Tools**

- Cable stripping knife
- Wire stripper
- Phillips screw driver
- Small screw driver

**Connecting lines to the terminal strip**

1. Open the module.

![Fig. 3-1 Terminal strip with the relay and current connections](image-url)
2 Screw the cable gland (pos. 1 in Fig. 3-1) with the sealing ring (pos. 2) into the module housing.

3 Loosen the coupling ring (pos. 3 in Fig. 3-1).

4 Feed the line through the cable gland in the module housing.

5 Connect the wires to the terminal strip. While doing so, pay attention to the specifications on the label located under the terminal strip.

6 Tighten the coupling ring (pos. 3 in Fig. 3-1).

**Warning**

No free wires must be allowed to project into the enclosure. Otherwise, there is a danger that safe areas could come into contact with dangerous voltages. This could result in life threatening electric shock when working with the IQ SENSORNET. Always cut off any wires that are not in use as closely as possible to the cable gland.

7 Close the module.
4  Settings

The combi output module has three relays outputs and three current outputs.

- Relay outputs operate as openers or closers.
- Current outputs provide a current that depends on the measured value.

On the terminal or Universal Transmitter, you can

- assign names to the outputs (with the 2020 XT system only, see section 4.2).
- link outputs with sensors (see section 4.3)
- delete links of outputs with sensors (see section 4.4)
- adjust outputs (see section 4.5 and section 4.6)
- check the condition of the outputs (see section 4.7)

Basic information on how to use relay outputs is given in section 4.1.

**Note**
The general operating principles are given in the relevant system operating manual or in the component operating manual of the terminal components.

Functions of current and relay outputs

**Relay output (see section 4.5)**

- System monitoring
- Sensor monitoring
- Limit indicator
- Frequency controller
- Pulse-width contr.
- Cleaning
- Sensor-controlled
- Manual control
- Alarm contact (with the 2020 XT system only)

**Current output (see section 4.6)**

- Recorder
- PID controller
- Fixed current value
4.1 Basic information on relay functions

In this chapter, you will find general basic information concerning the following relay functions:

- Monitoring (see section 4.1.1)
- Limit indicator (see section 4.1.2)
- Proportional output (see section 4.1.3)

4.1.1 Monitoring

When using a relay for monitoring, a relay action (Open, Close) occurs when certain states occur. This function is suitable, e.g. for the monitoring of errors in the system.

**Note**

For monitoring functions, use the relay preferably as an opener (see section 4.5.1). In the case of an error, the relay opens. As a result, the monitoring function operates even if, e.g. the supply voltage fails.
4.1.2 Limit indicator

With a limit indicator, a relay switches when a specified limiting value is exceeded or undercut.

Limit indicators can be used in the following way:

- Monitoring a limiting value using a relay:
  when a limiting value (upper or lower limiting value) is exceeded or undercut, a relay switches. The **Open** or **Close** relay actions are possible in each case (see page 4-4).

- Monitoring two limiting values using two relays:
  If the upper limiting value is exceeded or undercut, a relay switches, and if the lower limiting value is exceeded or undercut, another relay switches. The **Open** or **Close** relay actions are possible in each case (see page 4-4).

**Note**
If the simple monitoring function (Open, Close) with one or two relays is not sufficient, use proportional output (see section 4.1.3).
Monitor limiting values using one or two relays

Fig. 4-1 Switching points for relays with the function of a limit indicator

1. Upper limit value (relay 1) exceeded
2. Selected switching delay \(t_1\) for relay 1 expired
   Relay 1 switches
3. Hysteresis for upper limiting value (relay 1) undercut
4. Selected switching delay \(t_1\) for relay 1 expired
   Relay 1 switches back
5. Lower limit value (relay 2) undercut
   Selected switching delay \(t_2\) for relay 2 expired
   Relay 2 switches
6. Hysteresis for lower limiting value (relay 2) exceeded
   Selected switching delay \(t_2\) for relay 2 expired
   Relay 2 switches back

A switching delay \((t)\) can be set up for each relay for switching processes. This is the time period for which a limiting value must be exceeded before the relay switches. This prevents frequent switching if the measured values are close to the limiting value.
4.1.3 Proportional output

In the case of proportional output, a relay switches cyclically on and off in a defined measured value range (proportional range). At the same time, the relay switches with a:

- duration of operation that corresponds to the measured value (pulse-width output, see page 4-7) or
- switching frequency (frequency output, see page 4-8).

Proportional outputs can be used in the following way:

- Output with one relay:
  An output range is defined with a Start value and an End value. No output takes place above and below the output range (see page 4-6).

- Output with two relays:
  An output range is defined for each relay with a Start value and an End value. One relay outputs in the upper output range and a further relay in the lower output range (see page 4-6).
### Output with one relay

Switching frequency $f$ or Pulse width $v$

![Graph of Output with one relay](image)

Fig. 4-2 Output with one relay

### Output with two relays

Switching frequency $f$ or Pulse width $v$

![Graph of Output with two relays](image)

Fig. 4-3 Output with two relays

<table>
<thead>
<tr>
<th></th>
<th>Start value</th>
<th>End value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Measured value with a minimum pulse width or switching frequency</td>
<td>Measured value with a maximum pulse width or switching frequency</td>
</tr>
</tbody>
</table>
**Pulse width output**

The output of the pulse width is used, e.g. for controlling valves.

Pulse-width regulation changes the duration of operation (t\text{on}) of the output signal. Depending on the position of the measured value in the proportional range, the relay is operated for a longer or shorter time period.

\[
v = \left(\frac{t_{\text{on}}}{T}\right) \times 100\% \tag{1}
\]

\(v\) = pulse width, \(T\) = cycle duration, \(t_{\text{on}}\) = turn-on duration

- If the measured value is at the end of the proportional range (End value), the turn-on duration \(t_{\text{on}}\) is long, the turn-off duration is short. This means the relay operates for a longer period.
- If the measured value is at the beginning of the proportional range (Start value), the turn-on duration \(t_{\text{on}}\) is short, and the relay operates for a correspondingly shorter period.

**Note**

If the duration of the closing or opening pulse is shorter than 0.1 s, the relay remains open or closed for the complete cycle duration.
**Frequency output** Switching frequency output is used, e.g. for controlling dosing pumps.

In contrast to the pulse-width output, not the pulse width is modulated with frequency output but the switching frequency of the output signal. Depending on the position of the measured value in the proportional range, the relay is switched more often or less often.

![Diagram of relay output of frequency output](image)

While the selected switching duration \( t_{on} = 0.3 \text{ s} \) always remains constant, the switching frequency at which the relay switches changes depending on the measured value.

- If the measured value is at the end of the proportional range (End value), the switching frequency is higher.
- If the measured value is at the beginning of the proportional range (Start value), the switching frequency is low.
Characteristic curves

Through the selection of the Start value and End value, the proportional output can be operated with a positive or negative characteristic curve.

- **Positive characteristic curve:**
  Select the End value to be greater than the Start value.
  The turn-on duration or frequency increases with an increasing measured value (see page 4-10).

- **Negative characteristic curve:**
  Select the End value to be smaller than the Start value.
  The turn-on duration or frequency decreases with an increasing measured value (see page 4-11).

The maximum values for the pulse width or switching frequency are assigned to the End value and the minimum values for turn-on duration or frequency are assigned to the Start value.

---

**Fig. 4-6**  Positive characteristic curve

**Fig. 4-7**  Negative characteristic curve
**Positive characteristic curve**

The proportional output range begins above the initial value. If the proportional range is undercut or exceeded, the selected behavior comes into force.

**Fig. 4-8 Pulse width output**

**Pulse width \( v [\%] \)**

- Cycle duration \( T \)
- \( t_{on}, t_{off} \)
- Proportional band
- 90% 10%

**Fig. 4-9 Frequency output**

**Switching frequency \( f [1/min] \)**

- Maximum switching frequency
- 50% of maximum switching frequency

| 1 | Start value |
|   | Measured value with a minimum pulse width or switching frequency |
| 2 | End value |
|   | Measured value with a maximum pulse width or switching frequency |
**Negative characteristic curve**

The proportional output range begins below the initial value. If the proportional range is undercut or exceeded, the selected behavior comes into force.

---

---

**Fig. 4-10** Pulse width output

---

**Fig. 4-11** Frequency output

---

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
</table>
| 1 | Start value  
 Measured value with a minimum pulse width or switching frequency |
| 2 | End value  
 Measured value with a maximum pulse width or switching frequency |
4.2 Entering / editing the name of an output

For easier identification of the outputs, an individual name can be given to each output in the Edit list of outputs overview. This option is available with the 2020 XT system only.

1. Open the Settings menu with 📌.

2. Using 📌 and √, select and confirm the menu item, System settings -> Edit list of outputs. The Edit list of outputs display opens.

3. Highlight a name in the Name column with 📌 and confirm with √.

4. Select a letter, a numeral or a special character with 📌 and confirm with √.

5. Complete the name of the output and confirm with √.
4.3 Linking the output with a sensor

The following steps describe operation with the 2020 XT system. With the System 182 XT, the outputs of the DIQ/CR3 can be found directly under the Settings menu (see system operating manual of the DIQ/S 182 XT).

1. Open the Settings menu with S.
2. Using D and OK, select and confirm the menu item, System settings -> Settings of outputs and links. The Settings of outputs and links display opens.
3. Highlight the column with D and confirm with OK.
4. Highlight an output with D and confirm with OK. The Link with... display opens. The display shows a list of the sensors to which a link is possible.

5. Select a sensor with D and confirm with OK. The output is linked with the selected sensor.

**Note**

Outputs that are linked with sensors can be identified in the Ser. no. field of the Settings of outputs and links overview by the specification of the linked sensor.
4.4 Deleting a link with an output

If a link from a current or relay output with a sensor is no longer required, the link can be deleted.

The following steps describe operation with the 2020 XT system. With the System 182 XT, the outputs of the DIQ/CR3 can be found directly under the Settings menu (see system operating manual of the DIQ/ S 182 XT).

1. Open the Settings menu with ①.

2. Using ② and ④, select and confirm the menu item, System settings -> Settings of outputs and links. The Settings of outputs and links display opens.

3. Highlight the column & with ② and confirm with ④.

4. Highlight a linked output with ② and confirm with ④.

5. Select Erase link with ② and confirm with ④. A security prompt appears.

6. Select Erase link with ② and confirm with ④. The link is deleted.
4.5 Setting the relay outputs

The following steps describe operation with the 2020 XT system. With the System 182 XT, the outputs of the DIQ/CR3 can be found directly under the Settings menu (see system operating manual of the DIQ/S 182 XT).

1. Call up the measured value display with \( M \).
2. Open the Settings menu with \( F \).
3. Highlight the Settings of outputs and links menu item with \( \uparrow \) and confirm with \( \otimes \). The Settings of outputs and links display appears.
4. Highlight the Feature column with \( \downarrow \) and confirm with \( \otimes \).
5. Highlight a line for a relay output (R\( x \)) in the Feature column with \( \uparrow \) and confirm with \( \otimes \). The Settings of outputs and links display opens.
6. Highlight the Relay function menu item with \( \downarrow \) and confirm with \( \otimes \).
7. Select one of the functions in the following list with \( \uparrow \) and confirm with \( \otimes \).
As soon as a function is selected for a relay output, a relay action can be selected (see section 4.5.1).

### 4.5.1 Relay action

The following actions of the relay can be laid down in the Action setting:

<table>
<thead>
<tr>
<th>Settings</th>
<th>Explanations</th>
</tr>
</thead>
<tbody>
<tr>
<td>Open</td>
<td>The relay should open if any event occurs.</td>
</tr>
<tr>
<td>Close</td>
<td>The relay should close if any event occurs.</td>
</tr>
</tbody>
</table>

**Note**

Preferably set up the relay output as normally closed for monitoring functions (Action Open).
4.5.2 System monitoring

Function

The System monitoring enables to monitor system errors.

In order to set up the System monitoring function for a relay output, the relay output must not be linked with a sensor (see section 4.3).

It can be used to monitor the following system errors.

<table>
<thead>
<tr>
<th>Settings</th>
<th>Selection</th>
<th>Explanations</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power failure</td>
<td>On</td>
<td>Off</td>
</tr>
<tr>
<td>Communication</td>
<td>On</td>
<td>Off</td>
</tr>
<tr>
<td>Collective error message</td>
<td>On</td>
<td>Off</td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>For all functions of the System monitoring, the relay action is set to Open.</td>
</tr>
</tbody>
</table>

Collective error message

In the case of a Collective error message, the relay opens if one of the following malfunctions occurs:

- One of the sensors properly registered at the controller does not supply a valid main measured value
- One of the sensors properly registered at the controller does not supply a valid secondary measured value
- The monitoring combi output module has not received any new data from the controller for two minutes.

In any case, the relay remains open for 10 seconds and only closes when the malfunction is no longer present.

In the following cases, the relay does not open despite an invalid measured value:
The sensor is being calibrated
- The sensor is in the maintenance condition
- The sensor is being cleaned with the aid of a valve module in the system (compressed air operated cleaning system).

### 4.5.3 Sensor monitoring

**Function**
The Sensor monitoring function enables to monitor sensor errors and the maintenance condition.

In order to set up the Sensor monitoring function for a relay output, the relay output must be linked with a sensor (see section 4.3).

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Errors</td>
<td>Special</td>
<td>Special sensor errors are monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>All</td>
<td>All sensor errors (special ones and general ones) are monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>Off</td>
<td>Sensor errors are not monitored.</td>
</tr>
<tr>
<td>Mainten. Condition</td>
<td>On</td>
<td>Switching on and off the maintenance condition (see section 4.9) is monitored and can prompt a relay action.</td>
</tr>
<tr>
<td></td>
<td>Off</td>
<td></td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
<tr>
<td></td>
<td>Close</td>
<td></td>
</tr>
</tbody>
</table>

**Note**
Preferably set up the relay output as opener for monitoring functions (Action Open, see section 4.5.1).

Sensor messages include errors and information that are registered by the sensor.

**Special sensor errors**
The special sensor errors are sensor-dependent. Details of this are given in the component operating manual of the respective sensor.
4.5.4 Limit indicator

Function

The characteristic of the limit indicator is laid down in the Limit value UL, Limit value LL, Hysteresis UL and Hysteresis LL settings. The fundamentals of the function are described in the introductory chapter (see section 4.1.2).

In order to set up the Limit indicator function for a relay output, the relay output must be linked with a sensor (see section 4.3).

Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limit values</td>
<td>UL main variable, LL main variable, UL adjoining var., LL adjoining var.</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Limit value UL</td>
<td>Any upper and lower limiting value within the measuring range (sensor-dependent)</td>
<td>Minimum spacing between the upper and lower limiting value: 5 % of the measuring range</td>
</tr>
<tr>
<td>Limit value LL</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hysteresis UL</td>
<td>0 - 5% of the measuring range</td>
<td>Hysteresis for Limit value UL and Limit value LL.</td>
</tr>
<tr>
<td>Hysteresis LL</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

General sensor errors

- Init: can prompt a relay action for a short time, depending on the starting behavior of the system
- ----: Invalid measured value, or defective sensor
- Error: Communication with sensor interrupted
- OFL: Measuring range undercut or exceeded (overflow)
### Table: Setting Selection/Values

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Behavior at error</td>
<td>Open, Close, Unchanged</td>
<td>The relay opens, closes, or remains unchanged in case of system errors or sensor errors (see page 4-39).</td>
</tr>
<tr>
<td>Action</td>
<td>Open, Close</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
<tr>
<td>Switching delay</td>
<td>0 ... 3600 s</td>
<td>The time period for which a limiting value must be exceeded before the relay operates. Prevents frequent switching for measured values that are close to the limiting value.</td>
</tr>
</tbody>
</table>
### 4.5.5 Frequency controller

**Function**

The characteristic of the frequency output is laid down in the **Start value**, **End value**, **Frequency (f) min.** and **Frequency (f) max.** settings. The fundamentals of the function are described in the introductory chapter (see section 4.1.3).

In order to set up the Frequency controller function for a relay output, the relay output must be linked with a sensor (see section 4.3).

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable, Adjoining variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Start value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Minimum spacing: 5 % of the measuring range</td>
</tr>
<tr>
<td>End value</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency (f) min.</td>
<td>0 to 120 1/min</td>
<td>Minimum spacing: 10 1/min</td>
</tr>
<tr>
<td>Frequency (f) max.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency with error</td>
<td>0 to 120 1/min</td>
<td>In case of system errors or sensor errors (see page 4-39), the relay switches with the frequency specified.</td>
</tr>
<tr>
<td>Action</td>
<td>Open, Close</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
</tbody>
</table>

**Characteristic curve**

If a value is entered for **End value** that is greater than the **Start value**, the output has a positive characteristic curve.

In order to obtain a negative characteristic curve, a value must be entered for **End value** that is smaller than the value for **Start value**.
### 4.5.6 Pulse-width contr.

**Function**

The characteristic of the pulse width output is laid down in the Start value, End value, Pulse width (v) min. and Pulse width (v) max. settings. The fundamentals of the function are described in the introductory chapter (see section 4.1.3).

In order to set up the Pulse-width contr. function for a relay output, the relay output must be linked with a sensor (see section 4.3).

#### Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable Adjoining variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.). Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Start value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Minimum spacing: 5 % of the measuring range</td>
</tr>
<tr>
<td>End value</td>
<td></td>
<td>Minimum spacing: 10 % of the Cycle duration (T)</td>
</tr>
<tr>
<td>Pulse width (v) min.</td>
<td>0 ... 100 %</td>
<td>Minimum spacing: 10 % of the Cycle duration (T)</td>
</tr>
<tr>
<td>Pulse width (v) max.</td>
<td></td>
<td>Length of the switching period T ( T = (t_{on} + t_{off}) )</td>
</tr>
<tr>
<td>Cycle duration (T)</td>
<td>5 ... 100 s</td>
<td>In case of system errors or sensor errors (see page 4-39), the relay switches with the pulse-width specified.</td>
</tr>
<tr>
<td>Error pulse width</td>
<td>0 ... 100 %</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
<tr>
<td>Action</td>
<td>Open Close</td>
<td></td>
</tr>
</tbody>
</table>

**Characteristic curve**

You can specify the minimum and maximum pulse width (v). This determines the steepness of the characteristic curve of the output.
4.5.7 Cleaning

**Note**
When using the MIQ/CHV PLUS valve module, it is best to set the Cleaning function directly at the valve output (V) of the MIQ/CHV PLUS (see operating manual of the MIQ/CHV PLUS). The relay can then be used for other purposes.

**Function**
The Cleaning function enables the time controlled automatic start of the sensor cleaning function with the aid of a relay of the combi output module.
The relay controls the MIQ/CHV valve module and switches on or off the compressed air for the CH sensor cleaning head.

In order to set up the Cleaning function for a relay output, the relay output must be linked with a sensor (see section 4.3).

The relay assigned to the combi output module always works as a closer.

The cleaning cycle consists of Cleaning duration and Adjustment time.

During the cleaning cycle the Clean display flashes. The outputs linked with this sensor are frozen. The maintenance condition (see section 4.9) is active.

After the Cleaning duration, the relay is opened. During the following Adjustment time the outputs remain blocked. The outputs linked with this sensor are only released when the cleaning cycle is completed. The Clean display disappears. The maintenance condition is finished.

**Testing the operativeness**
You can test the operativeness of the cleaning system as follows: manually open or close the relay with the Manual control function (see section 4.5.9) and, while doing so, check the behavior of the cleaning system.

Alternatively, you can test the operativeness of the cleaning system by checking the performance of the function at the start time set up (reference time ± interval). To perform a test immediately, you can set the reference time so that the next cleaning will start in a few minutes (settings: see following table).
### Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reference time (h)</td>
<td>0 ... 23 h</td>
<td>Time at which a cleaning cycle is started. Further cleaning cycles will be performed at the times specified by the cleaning interval.</td>
</tr>
<tr>
<td>Reference time (min)</td>
<td>0 ... 60 min</td>
<td></td>
</tr>
<tr>
<td>Interval unit</td>
<td>1 .. 7 d</td>
<td>Selection of range and unit for the cleaning interval.</td>
</tr>
<tr>
<td></td>
<td>1 .. 24 h</td>
<td></td>
</tr>
<tr>
<td></td>
<td>5 .. 60 min</td>
<td></td>
</tr>
<tr>
<td>Cleaning interval</td>
<td>1/2/3/4/5/6/7 d</td>
<td>Repeat interval for the cleaning function: Time between the start time of a cleaning cycle and the start time of the next cleaning cycle*.</td>
</tr>
<tr>
<td></td>
<td>or:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1/2/3/4/6/8/12/24 h</td>
<td></td>
</tr>
<tr>
<td></td>
<td>or:</td>
<td></td>
</tr>
<tr>
<td></td>
<td>5/10/15/20/30/60 min</td>
<td></td>
</tr>
<tr>
<td>Cleaning duration</td>
<td>0 ... 300 s</td>
<td>Duration of the cleaning</td>
</tr>
<tr>
<td>Adjustment time</td>
<td>0 ... 900 s</td>
<td>Time extension to allow the sensor to adjust to the test sample after the cleaning.</td>
</tr>
</tbody>
</table>

* With short cleaning intervals, the adjustable values for the Cleaning duration and Adjustment time are limited. The following values apply:

<table>
<thead>
<tr>
<th>Cleaning interval</th>
<th>Cleaning duration</th>
<th>Adjustment time</th>
</tr>
</thead>
<tbody>
<tr>
<td>≤ 10 min</td>
<td>max. 60 s</td>
<td>max. 120 s</td>
</tr>
<tr>
<td>≤ 20 min</td>
<td>max. 180 s</td>
<td>max. 300 s</td>
</tr>
</tbody>
</table>

**Note**

With this, the cleaning times are fixed. They only change when the reference time is changed.

**Note**

The reference time and all further cleaning times relate to the date and time of the system clock. How to set the system clock is described in the system operating manual.
**Example**

<table>
<thead>
<tr>
<th>Setting</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reference time (h): 12</td>
<td>Reference time: 12:00 hours</td>
</tr>
<tr>
<td>Reference time (min): 0</td>
<td>This specifies the following start times:</td>
</tr>
<tr>
<td>Interval unit: 8 h</td>
<td>04:00, 12:00 and 20:00 hours</td>
</tr>
<tr>
<td>Cleaning interval:</td>
<td></td>
</tr>
</tbody>
</table>

**Fig. 4-16 Cleaning cycle**

1. Reference time
   - Start of a cleaning cycle (t1)
   - Start of the specified Cleaning duration (t1a)

2. End of the specified Cleaning duration (t1a)
   - Start of the specified Adjustment time (t1b)

3. End of the specified Adjustment time (t1b)
   - End of the cleaning cycle (t1)

4. Reference time ± Cleaning interval (t2)
   - Start of a cleaning cycle

**t1**
- Cleaning cycle = Cleaning duration (t1a) Adjustment time (t1b)
- Linked outputs are frozen.

**t2**
- Cleaning interval
Canceling the cleaning

A running cleaning cycle is canceled:

- Automatically
  - If the sensor switches to the inactive condition during the cleaning cycle
- Manually
  - By pressing
  - By switching on the maintenance condition

Each time the cleaning cycle is canceled, the relay opens immediately.

If the cleaning cycle is canceled automatically, the outputs linked to the sensor are released immediately.
If the cleaning cycle is canceled manually, the sensor is in the maintenance condition. The linked outputs are only released after the maintenance condition was terminated manually.

The next cleaning cycle will be performed at the time set up.

Note
In case of a power failure, all relays open. The cleaning cycle is canceled. The outputs linked with the sensor change to the non-active condition (see section 4.8.2). As soon as the power is available, the outputs are released again. The next cleaning cycle will be performed at the time set up.
4.5.8 Sensor-controlled

With the Sensor-controlled function, the relay is controlled by a linked sensor.

Requirements

- For the 2020 XT system, a controller with a software version from 2.80 up is required
- Sensor that transmits signals to trigger a cleaning cycle, e.g. UV/VIS sensor

Settings

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pulse length</td>
<td>Automatic</td>
<td>The duration of the air cleaning process is programmed in the sensor. The relay automatically takes over the cleaning duration from the sensor.</td>
</tr>
<tr>
<td></td>
<td>0,5 s</td>
<td>The relay finishes the cleaning after the selected interval.</td>
</tr>
<tr>
<td></td>
<td>1 s</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 s</td>
<td></td>
</tr>
<tr>
<td></td>
<td>3 s</td>
<td></td>
</tr>
</tbody>
</table>

Note

Settings of the cleaning process can be done in the Settings of sensors and diff. sensors menu of the respective sensor.
4.5.9 Manual control

**Function**

With the Manual control function, you can test the operativeness of an instrument that is connected to the relay. To do so, close or open the relay manually and, while doing so, check the behavior of the connected instrument.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Relay function</td>
<td>Manual control</td>
<td>The selected relay action is carried out with Save and quit.</td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
<tr>
<td></td>
<td>Close</td>
<td></td>
</tr>
</tbody>
</table>

**Note**

The settings for other functions in the Relay function menu, as for example Frequency controller and Pulse-width contr., are retained while the Manual control is carried out.

4.5.10 Alarm contact

**Note**

The Alarm contact function is only effective with systems with alarm function (System 2020 XT).

**Function**

The Alarm contact function triggers a relay action (close or open) if a specified alarm event occurs. The Alarm contact function is only available for relays that are not linked with a sensor. If necessary, an existing link has to be deleted.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Relay function</td>
<td>Alarm contact</td>
<td>The selected relay action is carried out with Save and quit.</td>
</tr>
<tr>
<td>Action</td>
<td>Open</td>
<td>Relay action (see section 4.5.1)</td>
</tr>
<tr>
<td></td>
<td>Close</td>
<td></td>
</tr>
</tbody>
</table>

**Note**

The setting up of alarms is described in the IQ SENSORNET system operating manual. Other possibilities of how to use the alarm function are described there as well.
4.6 Setting of current outputs

The following steps describe operation with the 2020 XT system. With the System 182 XT, the outputs of the DIQ/CR3 can be found directly under the Settings menu (see system operating manual of the DIQ/ S 182 XT).

1. Call up the measured value display with 
2. Open the Settings menu with 
3. Highlight the Settings of outputs and links menu item with and confirm with . The Settings of outputs and links display appears.
4. Highlight the Feature column with and confirm with .
5. Highlight a line for a current output (Cx) in the Feature column with and confirm with . The Settings of outputs and links display opens.
6. Highlight the Current output menu item with and confirm with .
7. Select a function with and confirm with .

Fig. 4-17  150 - Settings of outputs and links
**Function**

The measured values of the linked sensor at the current output are set up as current intensity in the Recorder application. The output of measured values is laid down in the Recorder type, Start value and End value settings.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Start value</strong></td>
<td>within the</td>
<td>Minimum spacing: 5 % of the measuring range</td>
</tr>
<tr>
<td><strong>End value</strong></td>
<td>measuring range</td>
<td></td>
</tr>
<tr>
<td><strong>Measured variable</strong></td>
<td>Main variable</td>
<td>Main variable designates the actual measured</td>
</tr>
<tr>
<td><strong>Attenuation</strong></td>
<td>0 ... 40 mA/s</td>
<td>Speed of change of the output current (mA/s) in</td>
</tr>
<tr>
<td><strong>Recorder type</strong></td>
<td>0 to 20 mA or</td>
<td>the case of an erratic change of the input</td>
</tr>
<tr>
<td></td>
<td>4 to 20 mA</td>
<td>signal.</td>
</tr>
</tbody>
</table>

8 Carry out the settings for the current output with 🟢 and ✅.

9 Highlight and confirm Save and quit with 🟢 and ✅. The new settings are stored.

### 4.6.1 Recorder

**Function**

The measured values of the linked sensor at the current output are set up as current intensity in the Recorder application. The output of measured values is laid down in the Recorder type, Start value and End value settings.
<table>
<thead>
<tr>
<th>I -&gt; OFL/UFL</th>
<th>Error</th>
<th>Current values outside the range between Start value and End value are considered as errors. The current output reacts as specified under Behavior at error (see below).</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Limitation</td>
<td>The current at the output is limited to the Start value or End value.</td>
</tr>
<tr>
<td>Behavior at error</td>
<td>Fixed current value</td>
<td>In case of system errors and sensor errors, and in case of measured values outside the range between Start value and End value, the current output supplies the specified fixed current value. Possible values: 0 ... 21 mA.</td>
</tr>
<tr>
<td></td>
<td>Unchanged</td>
<td>The current at the output remains unchanged.</td>
</tr>
</tbody>
</table>
### 4.6.2 PID controller

**Function**

With the PID controller function, you can use an output as a controller output. The controller can be configured as a Proportional controller with a switchable Integral and Derivative controller part (PID controller).

The control mode of the PID controller is described by the following equation:

\[
I_{\text{Controller}} = I_0 + K \left( x_e + \frac{I}{Ti} \int x_e dt + T_d \frac{dx_e}{dt} \right)
\]

with:

\[
K = \frac{I_{\text{max}} - I_{\text{min}}}{X_p}
\]

\[
x_e = x_{\text{nom}} - x_{\text{actual}}
\]

\[
I_{\text{min}} \leq I_{\text{Controller}} \leq I_{\text{max}}
\]

- \(I_{\text{Controller}}\): Current at the controller output at time \(t\)
- \(I_0\): Current at output if \(x_{\text{actual}} = x_{\text{nominal}}\)
- \(K\): Gain
- \(X_p\): Proportional band
- \(x_e\): Error signal
- \(x_{\text{actual}}\): Actual value (current measured value)
- \(x_{\text{nom}}\): Nominal value
- \(ti\): Integral control part
- \(td\): Derivative control part
- \(t\): Time
- \(I_{\text{min}}\): Lower current limitation
- \(I_{\text{max}}\): Upper current limitation

The adjustable control parameters are \(x_{\text{nominal}}, I_0, X_p, I_{\min}, I_{\max}, ti\) and \(T_d\) (see setting table on page 4-35).
By activating or deactivating the **Integral (ti)** and **Derivative (td)** controller part, the following controller types can be configured:

<table>
<thead>
<tr>
<th>Controller type</th>
<th>td [s]</th>
<th>ti [s]</th>
</tr>
</thead>
<tbody>
<tr>
<td>P controller</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>PI controller</td>
<td>0</td>
<td>1 to 9999</td>
</tr>
<tr>
<td>PD controller</td>
<td>1 to 9999</td>
<td>0</td>
</tr>
<tr>
<td>PID controller</td>
<td>1 to 9999</td>
<td>1 to 9999</td>
</tr>
</tbody>
</table>

**Characteristic curve of the proportional controller**

For a P controller, the interrelationship between the measured value and current I at the controller output forms the following characteristic curve:

For a P controller, the interrelationship between the measured value and current I at the controller output forms the following characteristic curve:

Current I [mA]

![Characteristic curve of the proportional controller](image)

**Fig. 4-18** Proportional controller (negative characteristic curve)

The proportional band $X_p$ is limited by the measuring range of the linked sensor. If a value is entered for the parameter $X_p$ that is greater than zero, the controller has a negative characteristic curve (example Fig. 4-18). To obtain a positive characteristic curve, a negative value must be entered for $X_p$. 
Application example

- Feedback control of the D. O. concentration
- Sensor: TriOxmatic 700 IQ (measuring range: 0 ... 60 mg/l)

### Control parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nominal value</td>
<td>4 mg/l</td>
</tr>
<tr>
<td>( X_p )</td>
<td>10 % of the measuring range or 6 mg/l</td>
</tr>
<tr>
<td>( I_{min} )</td>
<td>8 mA</td>
</tr>
<tr>
<td>( I_{max} )</td>
<td>14 mA</td>
</tr>
<tr>
<td>( I_0 )</td>
<td>12 mA</td>
</tr>
<tr>
<td>( t_i )</td>
<td>0 s (no ( I ) controller part)</td>
</tr>
<tr>
<td>( t_d )</td>
<td>0 s (no ( D ) controller part)</td>
</tr>
</tbody>
</table>

The control parameters form the following (negative) characteristic curve:

![Characteristic curve for application example](image)

The controller works with the following gain:

\[
K = \frac{6 \text{ mA}}{6 \text{ mg/l}} = 1 \text{ mA/mg/l}
\]
Within the proportional band, a concentration increase by 1 mg/l causes a decrease of the current output by 1 mA. If, for example, the measured concentration is 5 mg/l, 11 mA are output:

\[ I_{\text{Controller}} = 12 \, mA + I \frac{mA}{mg/l} \cdot (4 \, mg/l - 5 \, mg/l) \]

\[ I_{\text{Controller}} = 12 \, mA + I \frac{mA}{mg/l} \cdot (-1 \, mg/l) = 11 \, mA \]

The highest concentration with which the controller works within the proportional band is 8 mg/l (corresponding to \( I_{\text{min}} = 8 \, mA \)), the lowest one is 2 mg/l (corresponding to \( I_{\text{max}} = 14 \, mA \)).

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measured variable</td>
<td>Main variable</td>
<td>Main variable designates the actual measured parameter of the sensor (e.g. pH, oxygen, etc.).</td>
</tr>
<tr>
<td></td>
<td>Adjoining variable</td>
<td>Adjoining variable designates an additional measured parameter (e.g. temperature).</td>
</tr>
<tr>
<td>Nominal value</td>
<td>within the measuring range (sensor-dependent)</td>
<td>Nominal value the measured value is regulated to</td>
</tr>
<tr>
<td>Xp</td>
<td>5 ... 100 %</td>
<td>Proportional band of the controller. Negative values result in a positive characteristic curve.</td>
</tr>
<tr>
<td></td>
<td>-5 ... -100 %</td>
<td>of the measuring range</td>
</tr>
<tr>
<td>I_{\text{min}}</td>
<td>0 ... 20 mA</td>
<td>Lower current limitation *</td>
</tr>
<tr>
<td>I_{\text{max}}</td>
<td>0 ... 20 mA</td>
<td>Upper current limitation *</td>
</tr>
<tr>
<td></td>
<td></td>
<td>* Note: Spacing between I_{\text{min}} and I_{\text{max}}: at least 5 mA</td>
</tr>
<tr>
<td>Setting</td>
<td>Selection/Values</td>
<td>Explanation</td>
</tr>
<tr>
<td>--------------</td>
<td>------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Io</td>
<td>0 ... 20 mA</td>
<td>Current value on the output if the measured value equals the Nominal value</td>
</tr>
<tr>
<td>ti</td>
<td>0 ... 9999 s</td>
<td>Hold-back time: Integral part of the controller (0 = not effective)</td>
</tr>
<tr>
<td>td</td>
<td>0 ... 9999 s</td>
<td>Reset time: Derivative part of the controller (0 = not effective)</td>
</tr>
<tr>
<td>Behavior at error</td>
<td>Fixed current value</td>
<td>In the case of an error, the current output supplies the current value defined in the Current with error field (any in the range 0 ... 21 mA).</td>
</tr>
<tr>
<td></td>
<td>Unchanged</td>
<td>In the case of an error, the current on the output remains unchanged.</td>
</tr>
</tbody>
</table>
4.6.3 Fixed current value

**Function**

With the Fixed current value function, you can test the operativeness of the instruments connected to the outputs: output different current values to the output and, while doing so, check the behavior of the connected instrument.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Selection/Values</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current output</td>
<td>Fixed current value</td>
<td>Using Save and quit, the nominal amperage that was input as Inom is output.</td>
</tr>
<tr>
<td>Inom</td>
<td>0 ... 20 mA</td>
<td>The nominal amperage that is output.</td>
</tr>
</tbody>
</table>

**Note**

The settings for other functions in the Current output menu, as for example PID controller and Recorder, are retained while the Fixed current value is carried out.
4.7 Checking the status of the outputs

This function offers a simple overview of the states of all outputs of the combi output module.

For relays, the status open or closed is displayed.

For current outputs, the current value available at the output is displayed.

With the System 182 XT, you can recall the states of the outputs via the measured value and status display (see system operating manual of the DIQ/S 182 XT).

With the 2020 XT system, the function, 394 - Status of output channels, in the menu, Settings/Service/List of all components can be accessed as follows:

1 Call up the measured value display with \( M \).
2 Open the Settings menu with \( S \).
3 Highlight the Service menu item with \( D \) and confirm with \( C \). The Service dialog box opens.
4 Highlight the List of all components menu item with \( D \) and confirm with \( C \). The List of all components dialog box opens.
5 Select the required component (column Model, entry MIQ CR3) with \( D \) and confirm with \( C \). The 394 - Status of output channels window opens.

<table>
<thead>
<tr>
<th>No.</th>
<th>Name</th>
<th>Chan</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>011</td>
<td>LW Lüfter 1</td>
<td>R1</td>
<td>closed</td>
</tr>
<tr>
<td>011</td>
<td>LW Lüfter 1</td>
<td>R2</td>
<td>closed</td>
</tr>
<tr>
<td>011</td>
<td>LW Lüfter 1</td>
<td>R3</td>
<td>open</td>
</tr>
<tr>
<td>011</td>
<td>02-Belebung</td>
<td>C1</td>
<td>14.12 mA</td>
</tr>
<tr>
<td>011</td>
<td>02-Belebung</td>
<td>C2</td>
<td></td>
</tr>
<tr>
<td>011</td>
<td>02-Belebung</td>
<td>C3</td>
<td>6.65 mA</td>
</tr>
</tbody>
</table>

Return ESC

Fig. 4-20 394 - Status of output channels

6 Using \( M \) or \( ESC \), exit the 394 - Status of output channels window.
4.8 Behavior of linked outputs

4.8.1 Behavior in case of error

For linked relay outputs or current outputs, you can determine the behavior of the outputs in case of errors.

Depending on the use of the output, the behavior in case of errors is set in the following menus:

<table>
<thead>
<tr>
<th>Output</th>
<th>menu</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency controller</td>
<td>Frequency with error (see section 4.5.5)</td>
</tr>
<tr>
<td>Pulse-width contr.</td>
<td>Error pulse width (see section 4.5.6)</td>
</tr>
<tr>
<td>Recorder</td>
<td>Current with error (see section 4.6.1)</td>
</tr>
</tbody>
</table>

Error events

The defined behavior occurs in the case of the following events or conditions:

- The linked sensor does not supply a valid measured value (display of Init, Error, "-----", or OFL).
- Communication of the MIQ/CR3; DIQ/CR3 with the IQ SENSORNET controller is disturbed for longer than 2 minutes.
- The supply voltage for the MIQ/CR3; DIQ/CR3 is too low.
- In the Recorder function, the measured value of the linked sensor is outside the range between Start value and End value.

Freezing the states of the outputs

Independent of the specified behavior at error, the following conditions lead to the freezing of the output states:

- The linked sensor is in the maintenance condition (display of Cal, Clean, or a flashing measured value).
- Communication of the MIQ/CR3; DIQ/CR3 with the IQ SENSORNET controller is disturbed for a short time. After the malfunction has lasted for 2 minutes the output changes to the specified behavior in the case of an error.

Resumption of the normal function

The relay output or current output automatically returns to its normal state as soon as all error conditions are over and all conditions causing a freezing of outputs are cleared.
4.8.2  Behavior in non-operative condition

An output is non-operative when no function is activated for the output. An output becomes non-operative in case of

- Power failure
  (As soon as the supply voltage is sufficient again, the non-operative condition of the outputs ends. The outputs function as specified by the user again.)
- Erasing a link to a sensor
- Changing the Measuring mode sensor setting for a linked sensor
- Changing the Measuring range sensor setting for a linked sensor

**Note**
Before editing sensor settings a note appears on the display to inform you that links will be erased when you change the Measuring mode or Measuring range sensor setting.

<table>
<thead>
<tr>
<th>Settings in the non-active condition</th>
<th>Current output</th>
<th>Relay output</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Current: 0 A</td>
<td>Relay: Open</td>
</tr>
</tbody>
</table>
4.9 Maintenance condition of sensors

The maintenance condition of sensors serves to calibrate, clean, service and repair (remove and replace) sensors.

In the maintenance condition
- the system does not react to the current measured value or the condition of the selected sensor
- linked outputs are frozen
- sensor errors do not prompt changes in the conditions of linked outputs.

The maintenance condition is automatically activated
- during calibration. After calibration the sensor remains in the maintenance condition until the maintenance condition is switched off manually (see section 4.9.2)
- during the cleaning cycle (see section 4.5.7)

Switch on the maintenance condition manually when you want to clean, service or repair (remove and replace) a sensor (see section 4.9.1).

When you have finished cleaning, servicing or repairing the sensor, switch off the maintenance condition manually (see section 4.9.2).

Note
When a sensor is in the maintenance condition, the measured values or status indications of the sensor in the measured value display flash.
### 4.9.1 Switching on the maintenance condition

<table>
<thead>
<tr>
<th>Step</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Call up the measured value display with \texttt{m}.</td>
</tr>
<tr>
<td>2</td>
<td>Select the sensor you want to switch on the maintenance condition for with \texttt{d}. The measured values of the sensor do not flash.</td>
</tr>
<tr>
<td>3</td>
<td>Open the 300 - Display/Options menu with \texttt{ok}.</td>
</tr>
<tr>
<td>4</td>
<td>Using \texttt{d}, highlight the menu item, Switch maintenance condition on/off or Maintenance of sensor S0x and confirm with \texttt{ok}. A window that informs you about the maintenance condition opens up.</td>
</tr>
<tr>
<td>5</td>
<td>Confirm Continue with \texttt{ok}. The selected sensor is in the maintenance condition. Linked outputs are frozen.</td>
</tr>
<tr>
<td>6</td>
<td>Call up the measured value display with \texttt{m}. The measured values of the sensor flash.</td>
</tr>
</tbody>
</table>

### 4.9.2 Switching off the maintenance condition

<table>
<thead>
<tr>
<th>Step</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Call up the measured value display with \texttt{m}.</td>
</tr>
<tr>
<td>2</td>
<td>Select the sensor you want to switch off the maintenance condition for with \texttt{d}. The measured values of the sensor flash.</td>
</tr>
<tr>
<td>3</td>
<td>Open the 300 - Display/Options menu with \texttt{ok}.</td>
</tr>
<tr>
<td>4</td>
<td>Using \texttt{d}, highlight the menu item, Switch maintenance condition on/off or Maintenance of sensor S0x and confirm with \texttt{ok}. A window that informs you about the maintenance condition opens up.</td>
</tr>
<tr>
<td>5</td>
<td>Confirm Continue with \texttt{ok}. The maintenance condition of the selected sensor is switched off. Linked outputs are released.</td>
</tr>
<tr>
<td>6</td>
<td>Call up the measured value display with \texttt{m}. The measured values of the sensor do not flash.</td>
</tr>
</tbody>
</table>
5 Maintenance and cleaning

5.1 Maintenance

The combi output module does not require any special maintenance work. The general maintenance of IQ SENSORNET components is described in the IQ SENSORNET system operating manual.

5.2 Cleaning

The cleaning of IQ SENSORNET components is described in the IQ SENSORNET system operating manual.
6 Technical data

Note
General technical data on MIQ modules are given in the TECHNICAL DATA chapter of the IQ SENSORNET system operating manual.

Electrical data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nominal voltage</td>
<td>Max. 24 VDC via the IQ SENSORNET (for details, see the TECHNICAL DATA chapter of the IQ SENSORNET system operating manual)</td>
</tr>
<tr>
<td>Power consumption</td>
<td>3 W</td>
</tr>
<tr>
<td>Protective class</td>
<td>II</td>
</tr>
<tr>
<td>Overvoltage category</td>
<td>II</td>
</tr>
</tbody>
</table>

Instrument safety

<table>
<thead>
<tr>
<th>Applicable norms</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>- EN 61010-1</td>
<td></td>
</tr>
<tr>
<td>- UL 3111-1</td>
<td></td>
</tr>
<tr>
<td>- CAN/CSA C22.2 No. 1010.1</td>
<td></td>
</tr>
</tbody>
</table>

Terminal connections

<table>
<thead>
<tr>
<th>IQ SENSORNET connections</th>
<th>2 Additional connectable SENSORNET terminator (terminating resistor)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of relay contacts</td>
<td>3</td>
</tr>
<tr>
<td>Number of current outputs</td>
<td>3</td>
</tr>
<tr>
<td>Terminal type</td>
<td>Screw-type terminal strip, accessible by opening the lid</td>
</tr>
<tr>
<td>Terminal ranges</td>
<td>Solid wires: 0.2 ... 4.0 mm² AWG 24 ... 12 Flexible wires: 0.2 ... 2.5 mm²</td>
</tr>
<tr>
<td>Line cross-section of cables carrying mains voltage</td>
<td>Europe: 1.5 ... 4.0 mm² USA: 1.5 ... 4.0 mm² AWG 14 ... 12</td>
</tr>
<tr>
<td>Cable feeds</td>
<td>4 cable glands M16 x 1.5 on the underside of the module</td>
</tr>
</tbody>
</table>
## Relays

<table>
<thead>
<tr>
<th>Output</th>
<th>Physically separated from the IQ SENSORNET</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. switching voltage</td>
<td>250 VAC or 24 VDC</td>
</tr>
<tr>
<td>Max. switching current</td>
<td>5 A (AC and DC)</td>
</tr>
<tr>
<td>Installation requirements</td>
<td>Fuse rating on the operator side: Maximum 5 A</td>
</tr>
</tbody>
</table>
| Relay functions | - System monitoring  
- Sensor monitoring  
- Limit indicator  
- Frequency controller  
- Pulse-width contr.  
- Cleaning  
- Sensor-controlled  
- Manual control  
- Alarm contact (MIQ/CR3 only) |

## Current outputs

<table>
<thead>
<tr>
<th>Output</th>
<th>Physically separated from the IQ SENSORNET</th>
</tr>
</thead>
</table>
| Output current | Can be switched between 0 - 20 mA and 4 - 20 mA  
In the case of errors, can be set to: 0 ... 21 mA |
| Max. initial output voltage | 15 V, in the case of missing or incorrect burden |
| Max. load | 500 Ω |
| Accuracy | 0.3 % ± 50 μA |
| Functions | Programmable as:  
- Analog output  
- PID controller  
- Output with fixed current value (for test purposes) |
7 Indexes

7.1 Explanation of the messages

In this chapter you will find a list with all the message codes and corresponding message texts that may occur in the log book of the IQ SENSORNET system for the MIQ/CR3 output module.

Note

Information about
- Contents and structure of the log book and
- Structure of the message code

can be found in the LOG BOOK chapter of the IQ SENSORNET system operating manual.

Note

All message codes of the output module MIQ/CR3 or DIQ/CR3 end with the number "411".

7.1.1 Error messages

<table>
<thead>
<tr>
<th>Message code</th>
<th>Message text</th>
</tr>
</thead>
</table>
| EA4411       | Current output range undercut
|              | * Check process
|              | * Check settings and, if necessary, change them |
| EA5411       | Current output range exceeded
|              | * Check process
|              | * Check settings and, if necessary, change them |
| EI3411       | Burden resistor too large (> 500 Ohm) or current loop interrupted
|              | * Check burden, terminal connections and connection lines |

7.1.2 Info messages

The MIQ/CR3 or DIQ/CR3 output module does not send any info messages.
8 Contact Information

8.1 Ordering & Technical Support

Telephone: (800) 897-4151
(937) 767-7241
Monday through Friday, 8:00 AM to 5:00 PM ET

Fax: (937) 767-9353 (orders)
(937) 767-1058 (technical support)

Email: environmental@ysi.com

Mail: YSI Incorporated
1725 Brannum Lane
Yellow Springs, OH 45387
USA

Internet: www.ysi.com

When placing an order please have the following information available:

YSI account number (if available) Name and Phone Number
Model number or brief description Billing and shipping address
Quantity Purchase Order or Credit Card

8.2 Service Information

YSI has authorized service centers throughout the United States and Internationally. For the nearest service center information, please visit www.ysi.com and click ‘Support’ or contact YSI Technical Support directly at 800-897-4151.

When returning a product for service, include the Product Return form with cleaning certification. The form must be completely filled out for an YSI Service Center to accept the instrument for service. The Product Return form may be downloaded at www.ysi.com and clicking on the ‘Support’ tab.
1) The tissue in plants that brings water upward from the roots;
2) a leading global water technology company.

We’re 12,500 people unified in a common purpose: creating innovative solutions to meet our world’s water needs. Developing new technologies that will improve the way water is used, conserved, and re-used in the future is central to our work. We move, treat, analyze, and return water to the environment, and we help people use water efficiently, in their homes, buildings, factories and farms. In more than 150 countries, we have strong, long-standing relationships with customers who know us for our powerful combination of leading product brands and applications expertise, backed by a legacy of innovation.

For more information on how Xylem can help you, go to www.xyleminc.com